



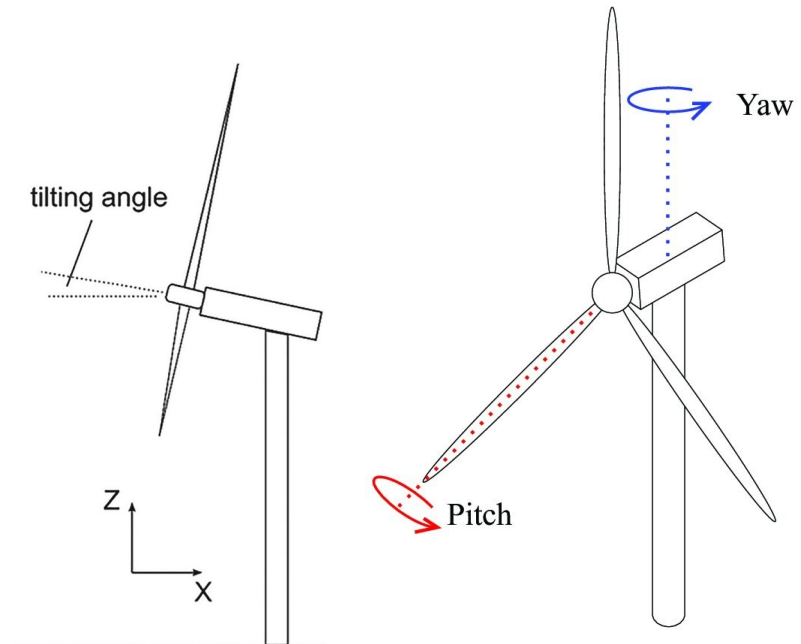
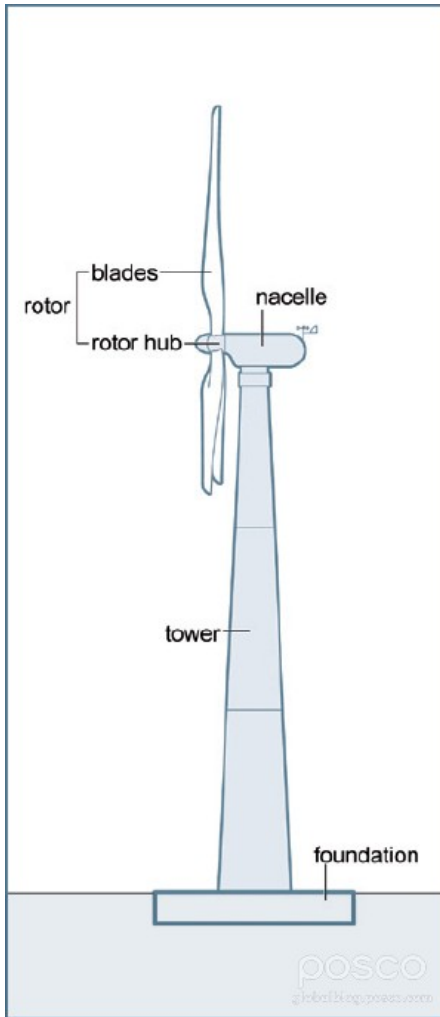
Wind Turbine Model



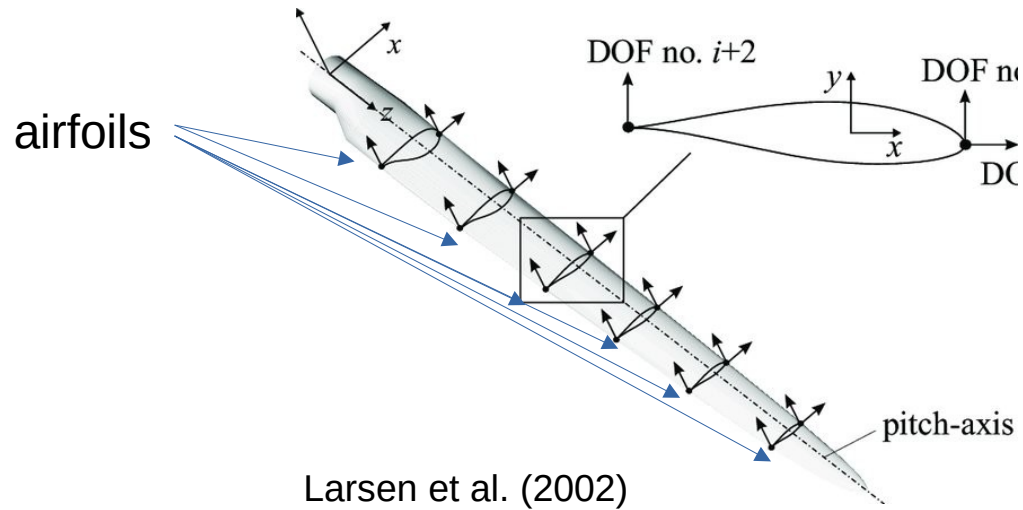
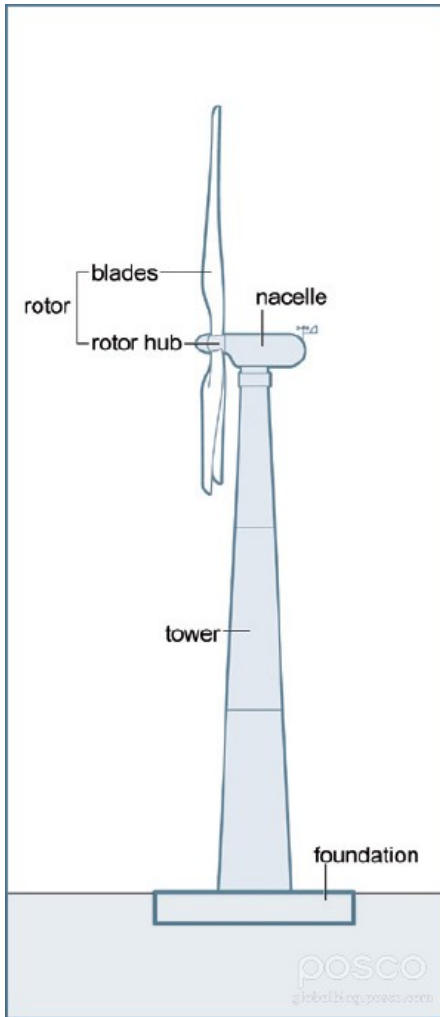
Institute of Meteorology and Climatology, Leibniz Universität Hannover

Degrees of freedom

- Yaw angle (horizontal angle of attack to rotor axis)
 - Blade Pitch (Rotation of blades to adjust rotation)
 - Tilt angle (vertical angle of attack to rotor axis)
- (+ pitch and roll for tower with offshore floating foundations)

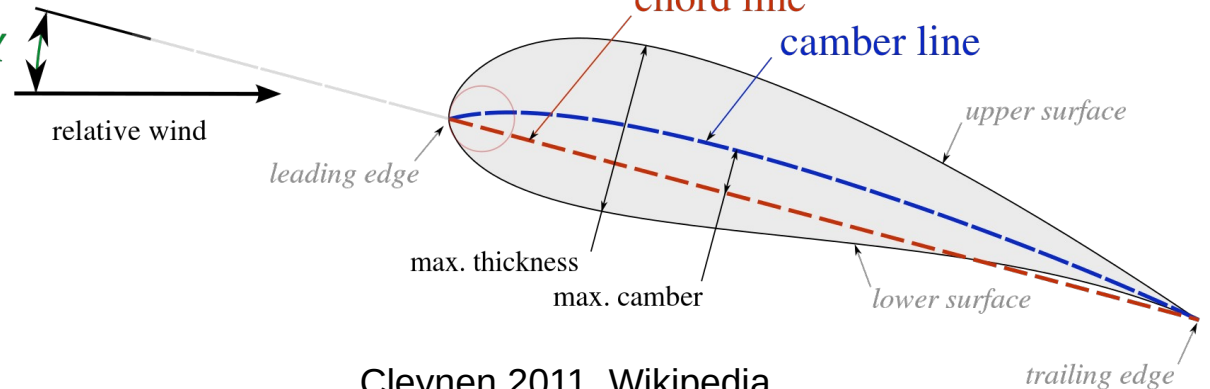


Wind turbine basics



angle of attack

α



Cleynen 2011, Wikipedia

Actuator Line Model (ALM)

- Based on blade element momentum (BEM) method
- Rotors treated as lines, divided into segments
- Lift and drag force are calculated for each segment Δr :

$$F_{L_{b,r}} = \frac{1}{2} \rho C_L V_{rel}^2 c \Delta r$$

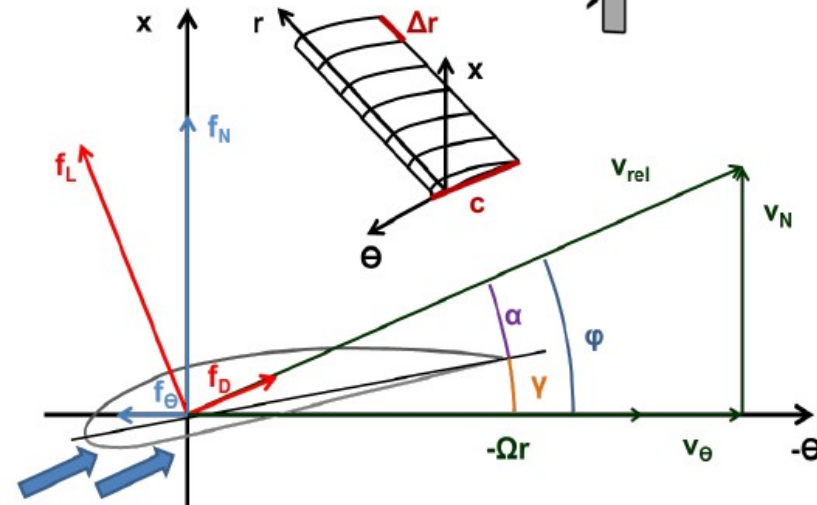
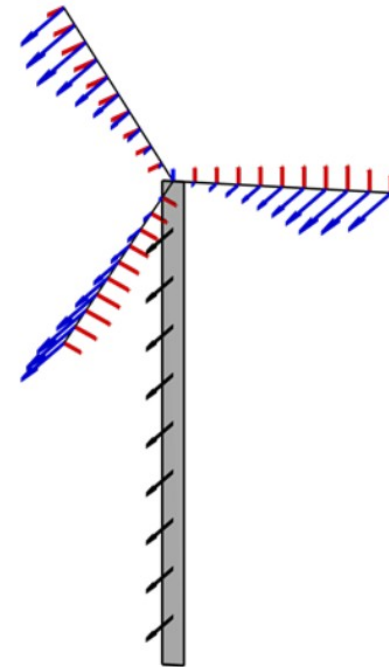
$$F_{D_{b,r}} = \frac{1}{2} \rho C_D V_{rel}^2 c \Delta r$$

- Lift C_L and drag C_D coefficients from look-up tables
- Projection on axial (F_N - Torque) and

$$F_{\theta_{b,r}} = F_{L_{b,r}} \sin \varphi + F_{D_{b,r}} \cos \varphi$$

$$F_{N_{b,r}} = F_{L_{b,r}} \cos \varphi + F_{D_{b,r}} \sin \varphi$$

$$\varphi = \arctan \left(\frac{V_N}{\Omega r - V_\theta} \right)$$

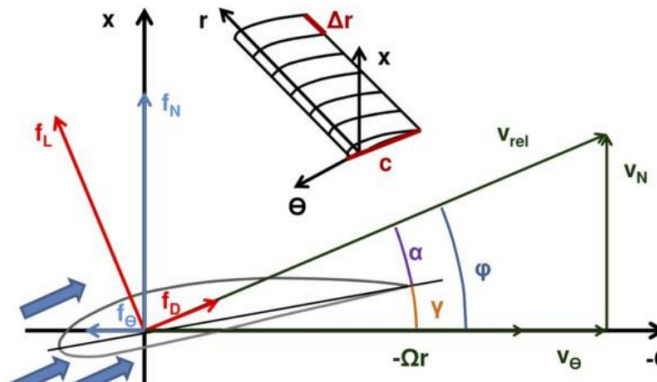


Rotating Actuator Disk Model (ADM-R)

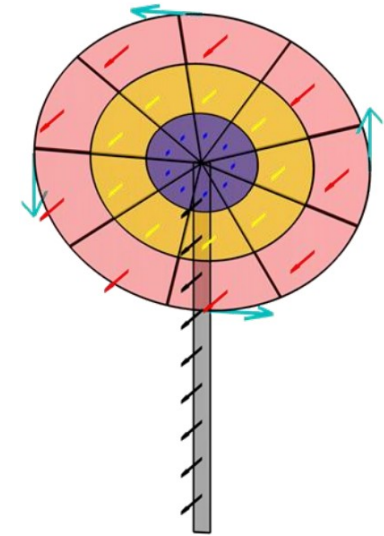
- Rotor disk instead of lines (→ time step issue solved)
- Rotor plane is permeable disk
- Forces are not uniformly distributed (BEM forces)
- (similar to Wu & Porte-Agel, 2011)
- Rotor plane divided into rings and segments
- Lift and drag forces are calculated for each segment:

$$f_l = \frac{1}{2} \rho U_{rel}^2 c_l(\alpha) \frac{N_b c}{2 \pi r_{seg}} \quad \text{perpendicular to inflow}$$

$$f_d = \frac{1}{2} \rho U_{rel}^2 c_d(\alpha) \frac{N_b c}{2 \pi r_{seg}} \quad \text{parallel to inflow}$$



(percentage of circumference that is covered with blades)



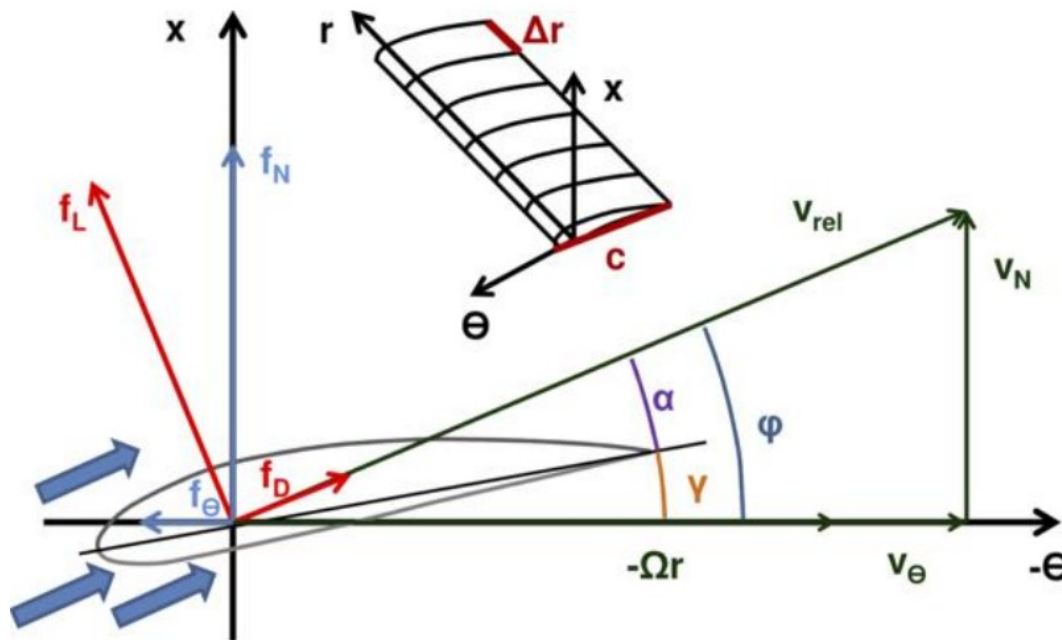
- ρ air density
- U_{rel} relative velocity
- c_l lift coefficient
- c_d drag coefficient
- α angle of attack
- N_b number of blades
- c chord length
- r_{seg} radial position of the segment
- $\frac{N_b c}{2 \pi r_{rot}}$ solidity factor

Rotating Actuator Disk Model (ADM-R)

- Projection on axial (f_N) and tangential (f_θ) directions as for ALM:

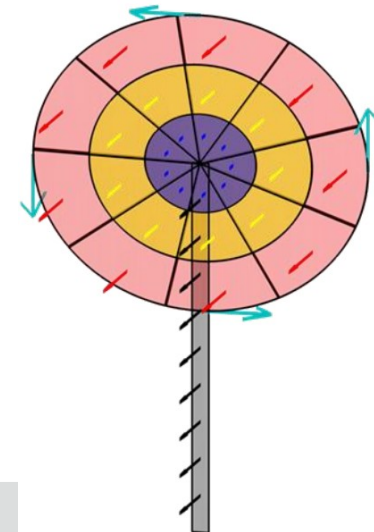
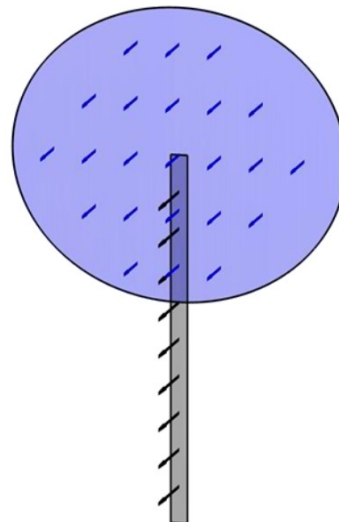
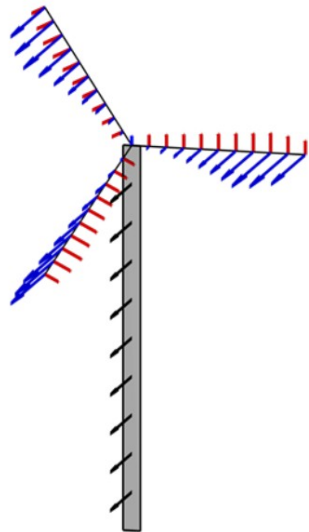
$$f_N = f_l \cos \phi + f_d \sin \phi \quad f_\theta = f_l \sin \phi - f_d \cos \phi$$

- Smearing to a Gaussian kernel to avoid numerical instabilities



Overview of typical parameterizations

ALM	ADM	ADM-R
Actuator Line Model (Calaf et al. 2010)	Actuator Disk Model (Troldborg 2008)	Actuator Disk Model with Rotation
Local forces (lines) (BEM equations)	Spatially constant loads	Local forces (segments) (BEM equations)
Rotation (resolved blades)	No rotation	Rotation (blades not resolved)
Very slow (small time step)	Very fast	Fast (significantly faster than ALM)



Overview of typical parameterizations

- Drag force approach:

$$F_{tower} = -\frac{1}{2} \rho C_{D_{tower}} V_{ref}^2 \quad V_{ref} = V_{local} \quad C_{D_{tower}} = 1.2$$

$$F_{nacelle} = -\frac{1}{2} \rho C_{D_{nacelle}} V_{ref}^2 \quad V_{ref} = V_{rotor} \quad C_{D_{nacelle}} = 0.85$$

- Forces are added to the axial component of the forces generated by the rotor

How to use the WTM

- Add NAMELIST **&wind_turbine_parameters**

```
&wind_turbine_parameters
...
n_turbines = 2,
hub_x = 400.0, 400.0,
hub_y = 500.0, 1500.0,
...
/
```

- For all available parameters refer to:

https://docs.palm-model.org/23.04/Reference/LES_Model/Namelists/#wind-turbine-parameters

- Add file **<job_identifier>_wtm**, that contains rotor blade data:
 - airfoil, chord and twist distribution along the blade
 - lift and drag coefficients for used airfoils
 - File with data for the NREL 5MW turbine is available at:

/palm_model_system/packages/palm/model/tests/cases/wind_turbine_model/
INPUT/wind_turbine_model_wtm

▪ NREL 5 MW Reference Turbine

- Detailed data about the rotor blades is needed for ADM-R (and ALM), but usually confidential
- PALM-WTM is this shipped with the NREL 5-MW reference offshore turbine (Jonkman et al. 2009)
- Representative characteristics for current multi-MW turbines
 - } Hub height: 90 m
 - } Rotor diameter: 126 m
 - } Nacelle diameter: 3 m
 - } Tower diameter: 4 m
 - } $\Omega = 12.1$ rpm
 - } C_L and C_D from look-up tables (depend on angle of attack and distance to hub)
 - } Chord and pitch angles from look-up tables

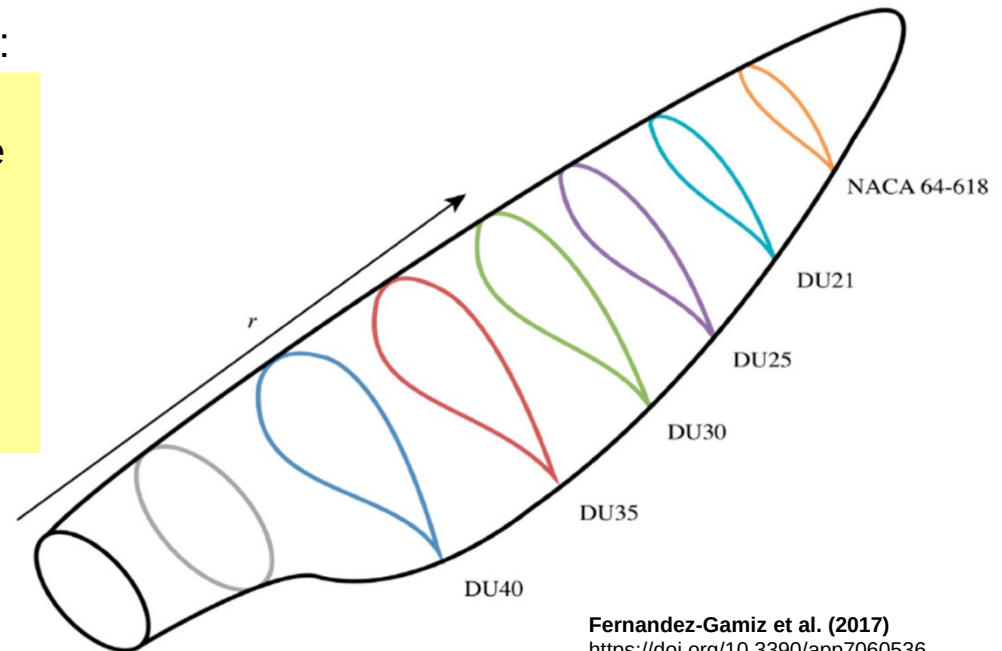
Rotor blade data in _wtm-file (1/2)

- Assign airfoils to radial positions along the blade:

```
# Tablefiles for nrel5MW
# Table 1: Distribution table
# Assigns the airfoils 1-8 to positions along the blade
0.0      1.5      0      0
1.5      5.6      1      1
5.6      8.3      1      2
...      ...
```

- Define twist angle and chord length:

```
# Table 2: Layout file
# Physical layout of the blade
# Pos[m] twist[deg] chord[m]
...      ...      ...
15.9     11.480    4.652
20.0     10.162    4.458
24.1     9.011   4.249
...      ...      ...
```

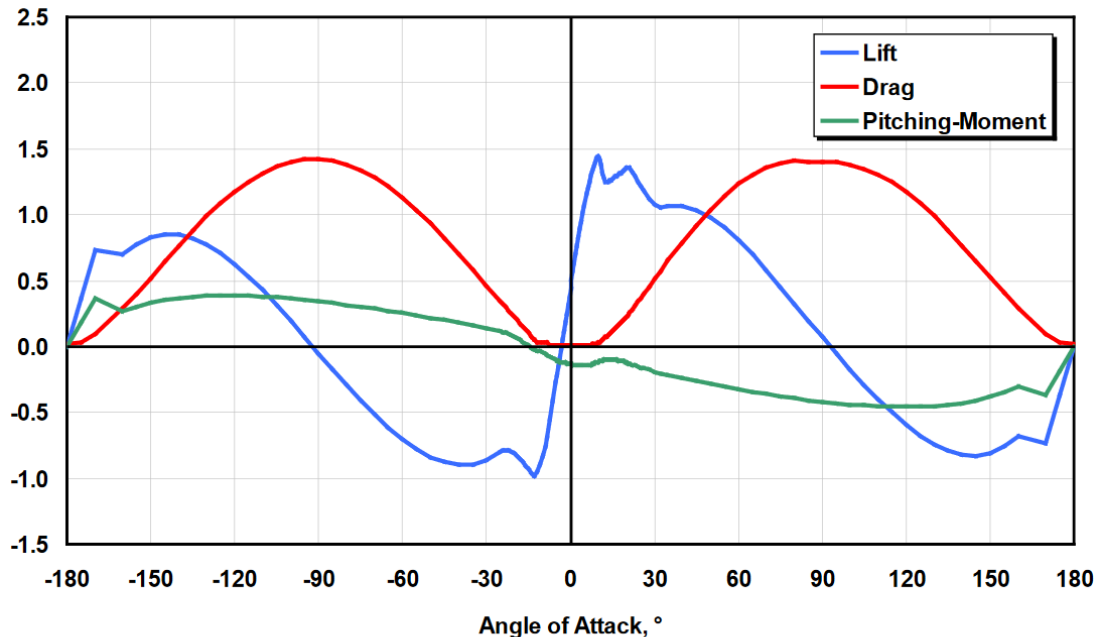


Fernandez-Gamiz et al. (2017)
<https://doi.org/10.3390/app7060536>

Rotor blade data in _wtm-file (2/2)

- Define lift and drag coefficients for each airfoil and angle of attack:

```
# Table 3: Lift and drag coefficients for airfoils 1-8
# alpha    ... C_l_3    C_d_3    C_l_4    C_d_4    ...
#
-180.00    ... 0.000    0.0602    0.000    0.0407    ...
-175.00    ... 0.218    0.0699    0.223    0.0507    ...
-170.00    ... 0.397    0.1107    0.405    0.1055    ...
...
```



Corrected coefficients of the DU25 airfoil

Jonkmann et al. (2009) DOI:
[10.2172/947422](https://doi.org/10.2172/947422)

Most important parameters

Wind turbine controller

- Generator torque **speed controller (Jonkman et al. 2009)**
 - } Must be adjusted for other turbines
 - } Most properties can be adjusted via Fortran NAMELIST
- **Pitch controller**
- Active and automatic **yaw controller**
- All controllers can be switched on/off:
 - } *speed_control = .F./.T.*
 - } *pitch_control = .F./.T.*
 - } *yaw_control = .F./.T.*

Most important parameters

- single parameters, that are valid for all turbines:
 - `n_turbines` = 2 number of wind turbines
 - `pitch_control` = `.TRUE.` activate pitch control
 - `yaw_control` = `.TRUE.` activate yaw control

- list parameters, individual for each turbine:
 - `hub_x` = 400.0, 400.0, x-coordinate of the hub
 - `hub_y` = 500.0, 1500.0, y-coordinate of the hub
 - `hub_z` = 90.0, 90.0, z-coordinate of the hub (hub height)
 - `rotor_radius` = 63.0, 63.0, rotor radius

Output files

- One output file with time series of operational data of all turbines is saved in `/<job_Identifier>/OUTPUT/<job_Identifier>_wtm.nc`
- operational data are e.g.:
 - rotational speed
 - torque
 - power
 - blade pitch angle
 - yaw angle
 - ...

Suitable setup for wind turbine simulations

- Use non-cyclic boundary conditions and the turbulence recycling method:
 - Be aware of the blockage effect:
 - Ensure that the wind turbines have enough distance to the recycling plane
 - 1 – 10 km required, depending on wind farm size and meteorological setup

```
&initialization_parameters
  bc_lr          = 'dirichlet/radiation',
  initializing_actions = 'cyclic_fill',

  turbulent_inflow      = .TRUE.,
  recycling_width       = 4000.0,
  inflow_damping_height = 700.0,
/
```

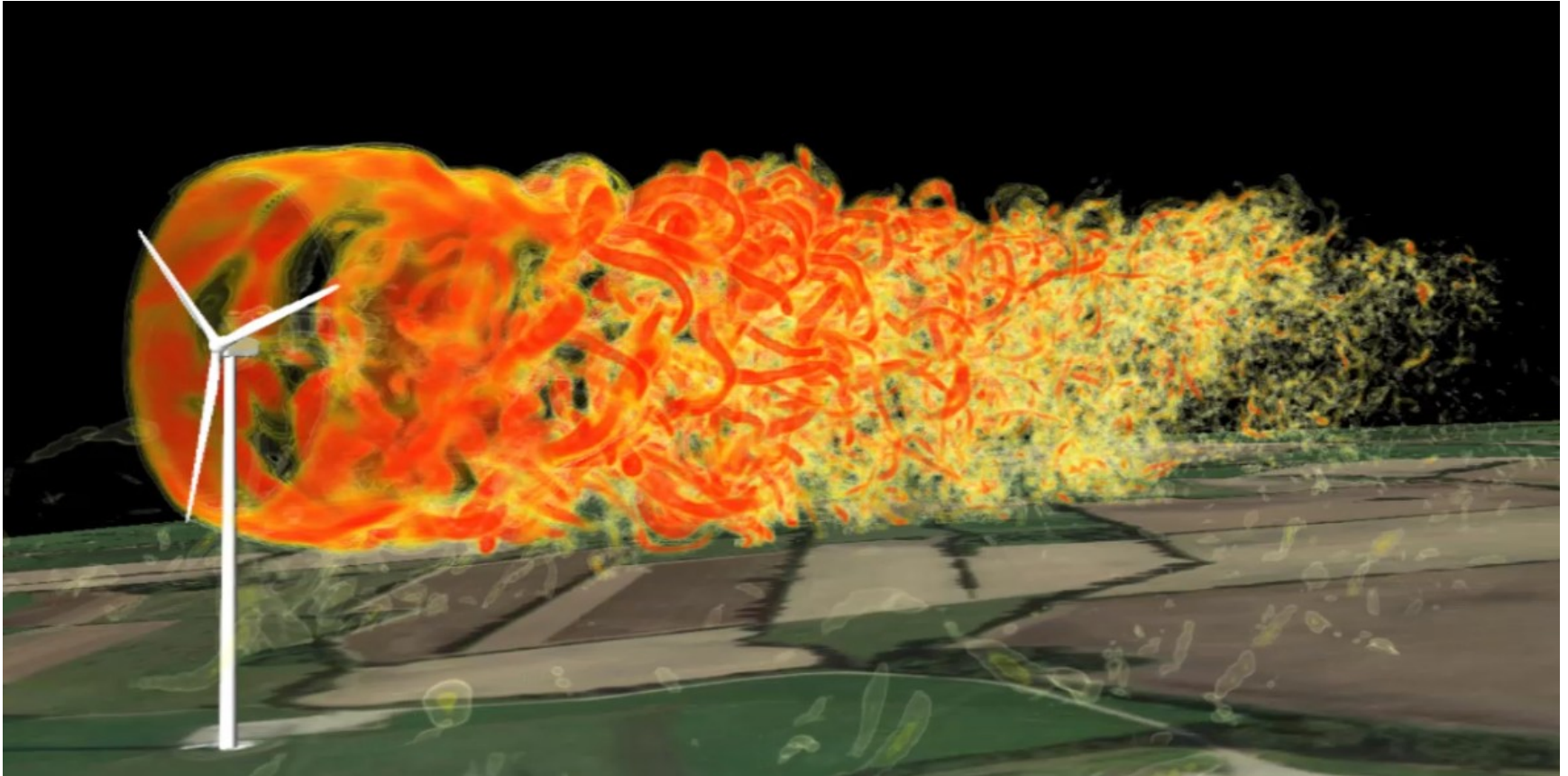
- Use non-cyclic boundary conditions and the synthetic turbulence generator:
 - no experience so far

Additional notes

PALM has two wind turbines included

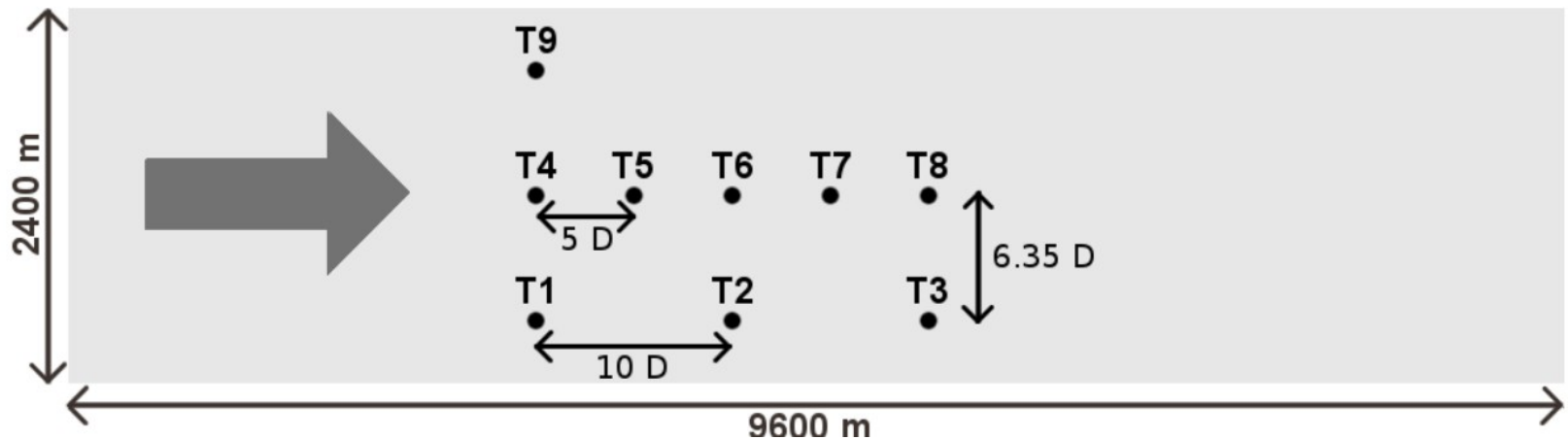
- 5 MW onshore NREL Reference turbine (available in the palm tests, see previous slides)
- 15 MW offshore IEA Reference turbine (will be used in the wind turbine exercise, currently not available in the PALM repository!)

ADM-R in PALM: Visualization



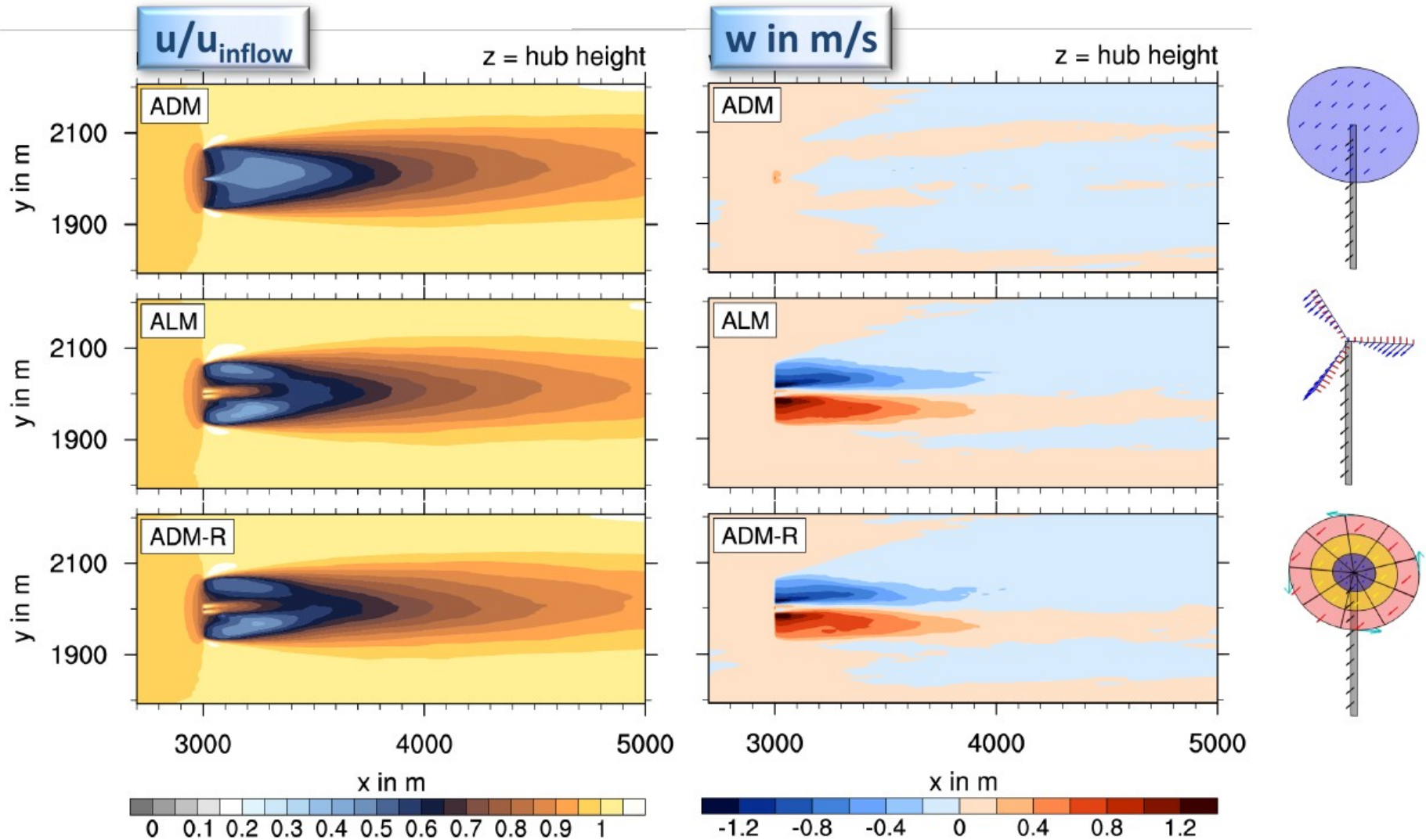
PALM-WTM validation/comparison

- PALM simulation of an idealized wind farm

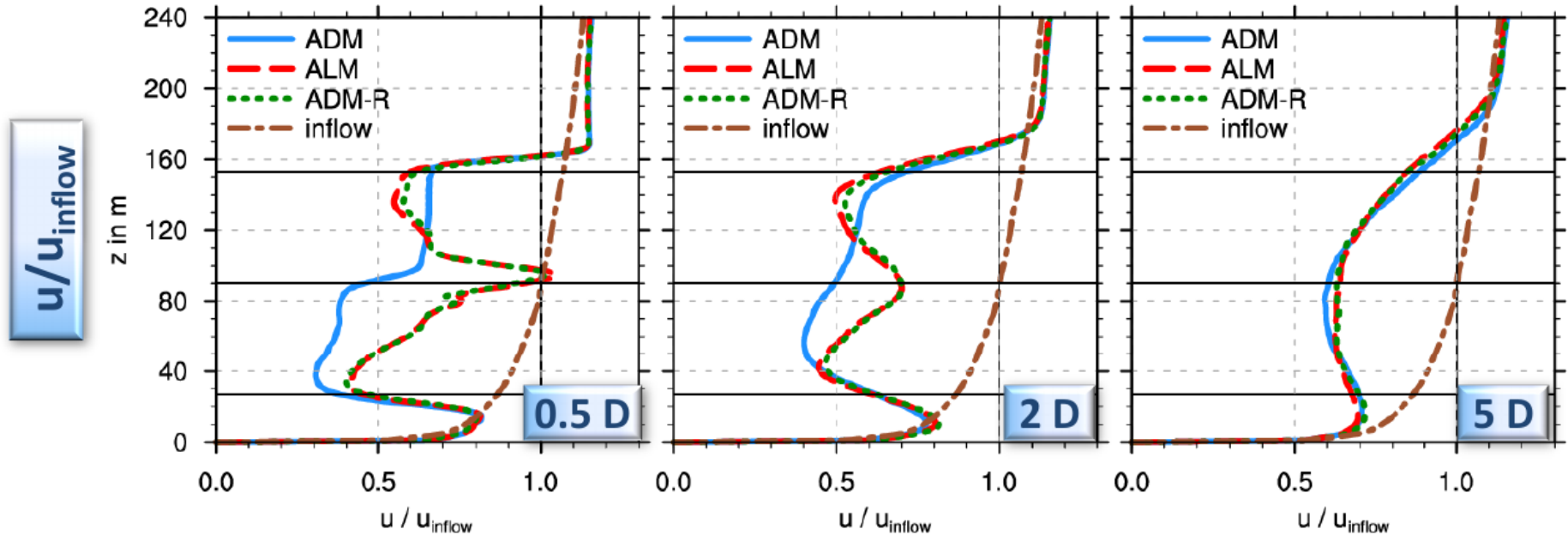


- Offshore conditions
 - } $z_0 = 0.0002 \text{ m}$, $\langle u \rangle_{\text{hub}} = 8 \text{ m/s}$
 - } Neutral stratification
- Non-cyclic horizontal boundary conditions with turbulent inflow

Validation: single wake (T9)

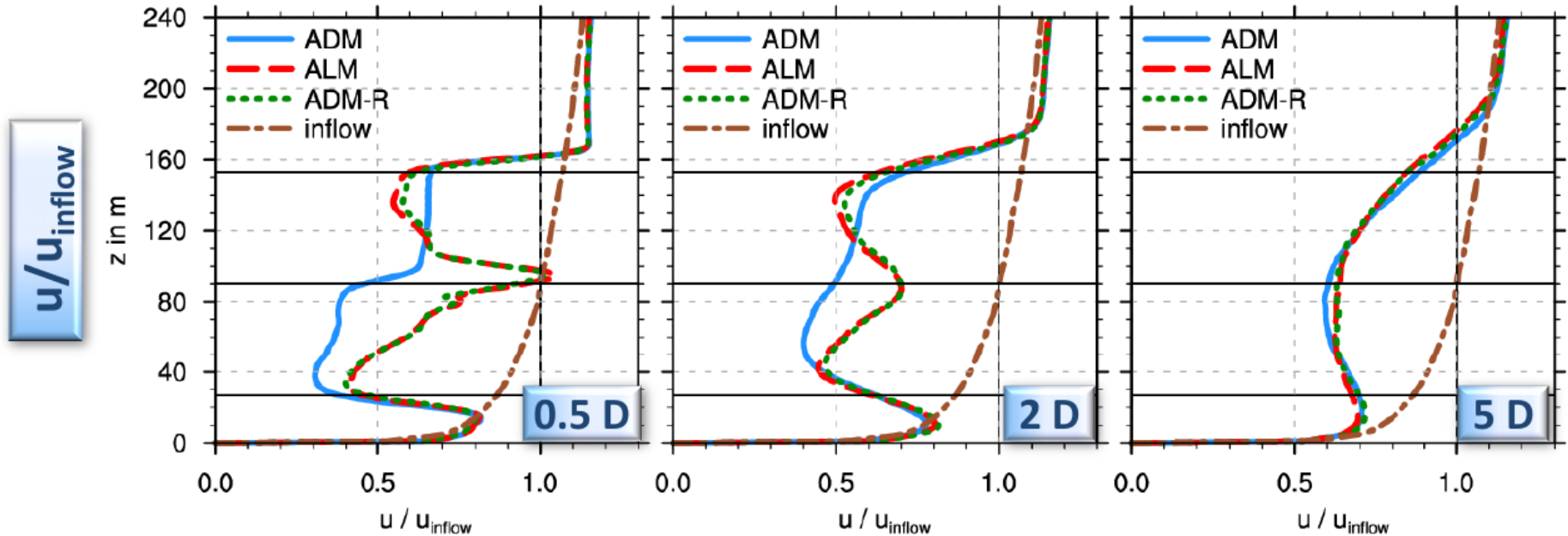


Validation: single wake (T9)



- ALM and ADM-R give almost identical results!
- Near wake is only reproduced ALM and ADM-R

Validation: single wake (T9)

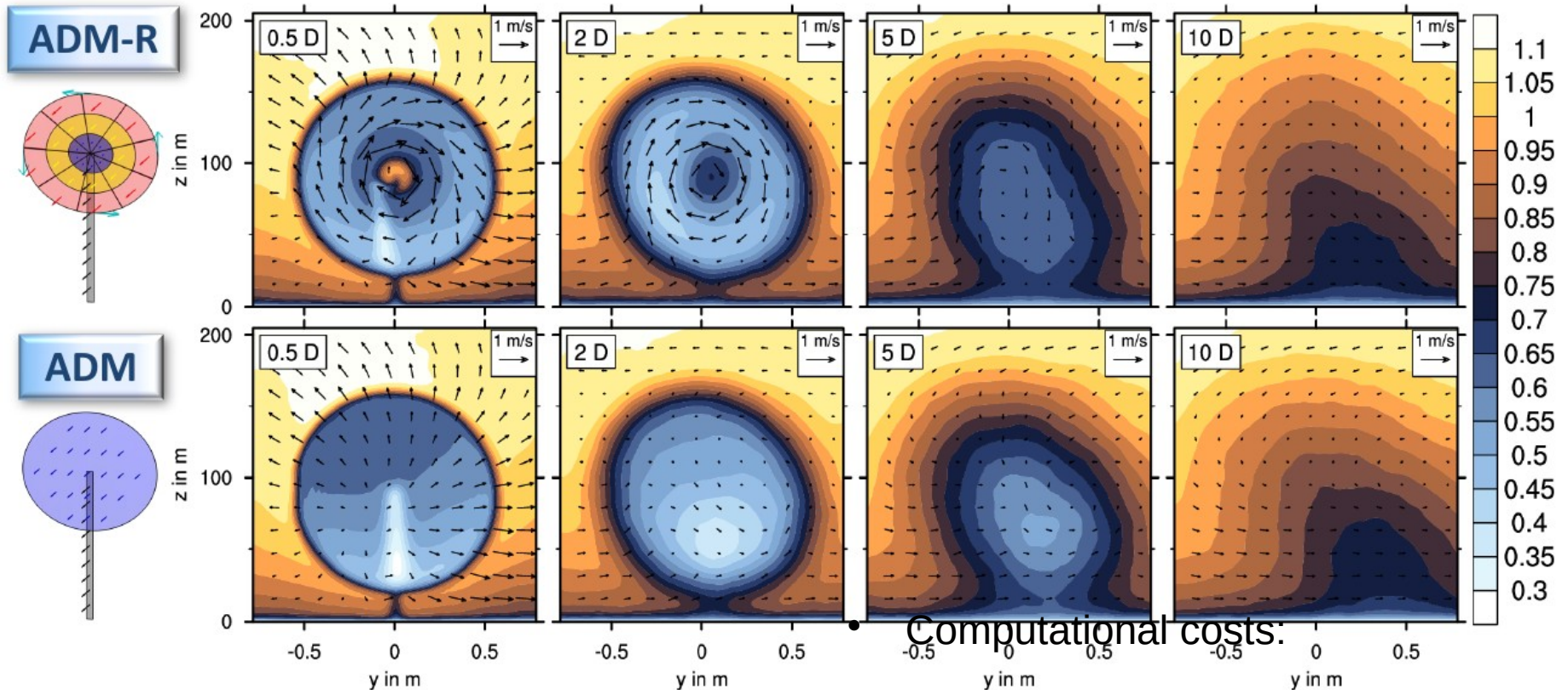


- ALM and ADM-R give almost identical results!
- Near wake is only reproduced ALM and ADM-R

- Computational costs:

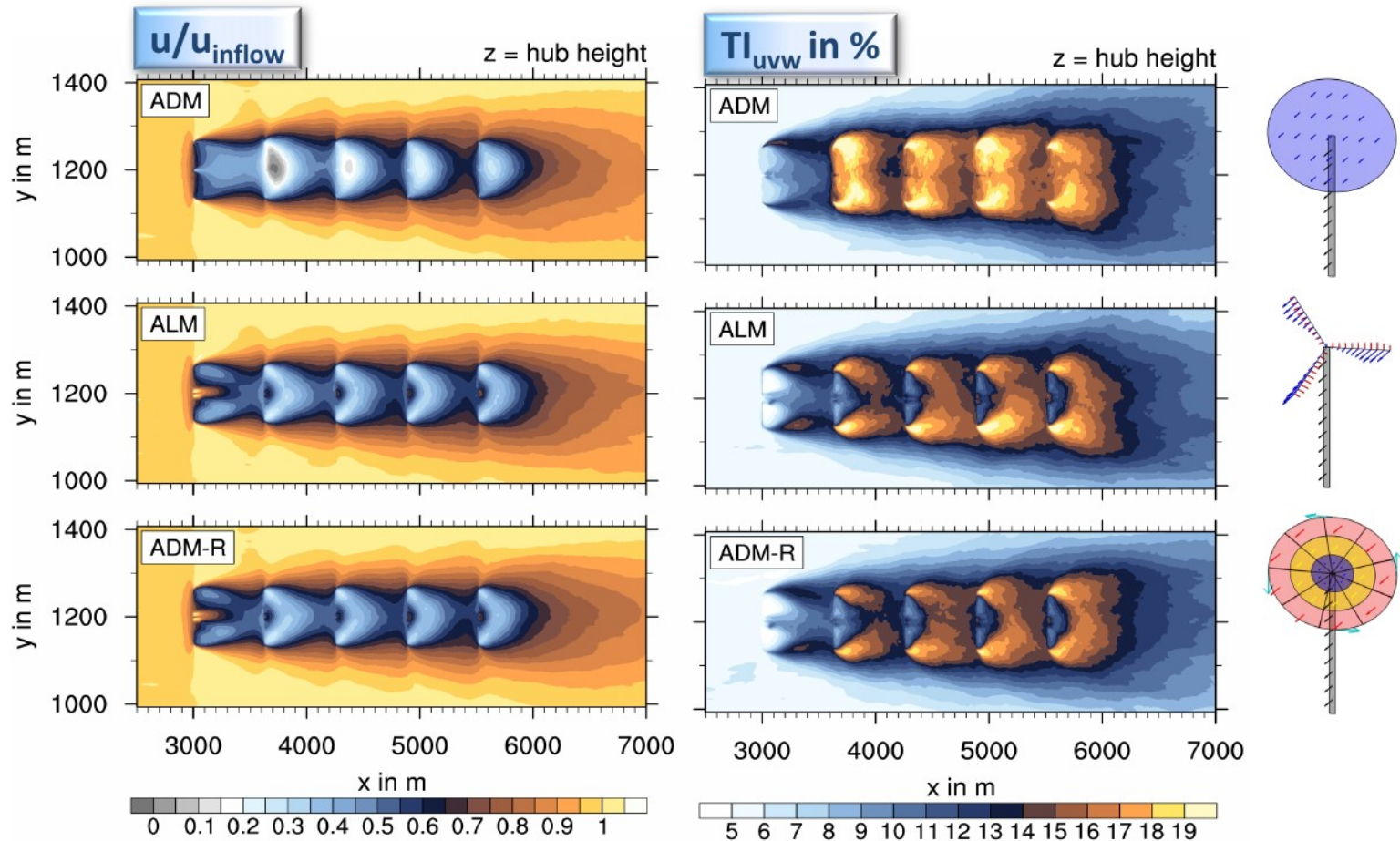
	ADM	ALM	ADM-R
$\Delta = 8 \text{ m}$	1	12.8	1.5
$\Delta = 4 \text{ m}$	1	8.1	2.0
$\Delta = 2 \text{ m}$	1	4.1	2.7

Validation: single wake (T9)

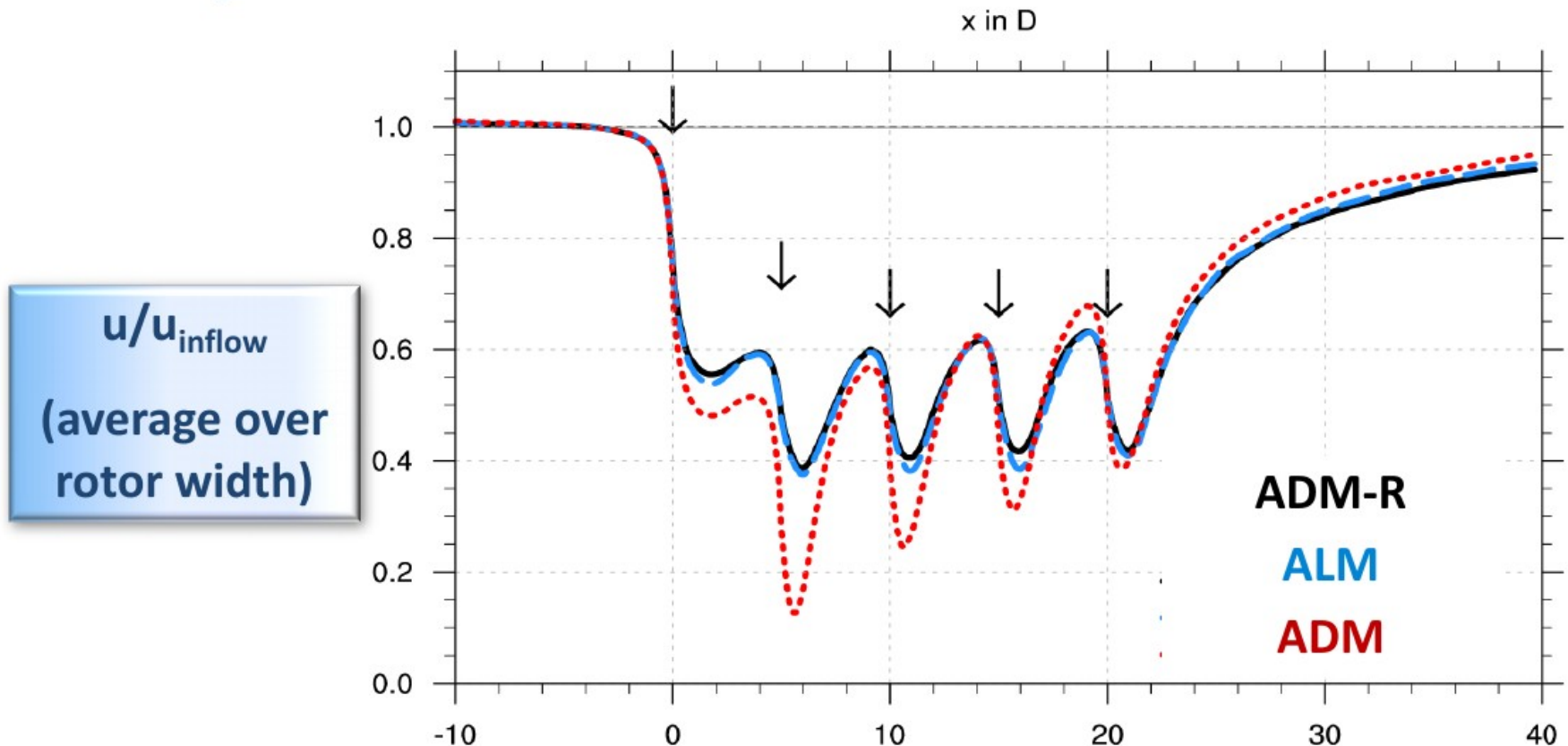


- ADM does not capture near wake and wake rotation
- Differences become small in the far wake

Validation: multiple wakes (T4-T8)

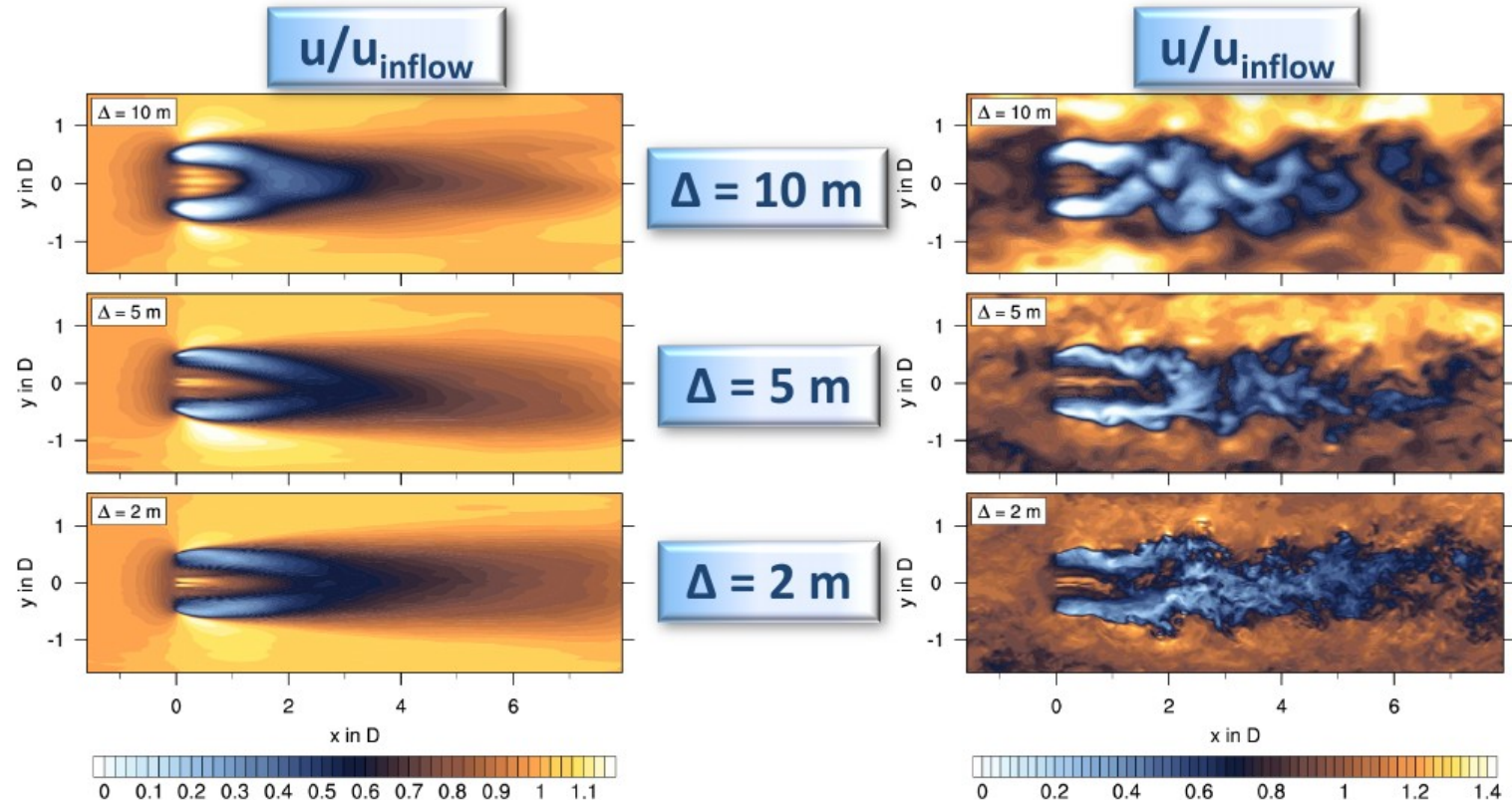


Validation: multiple wakes (T4-T8)



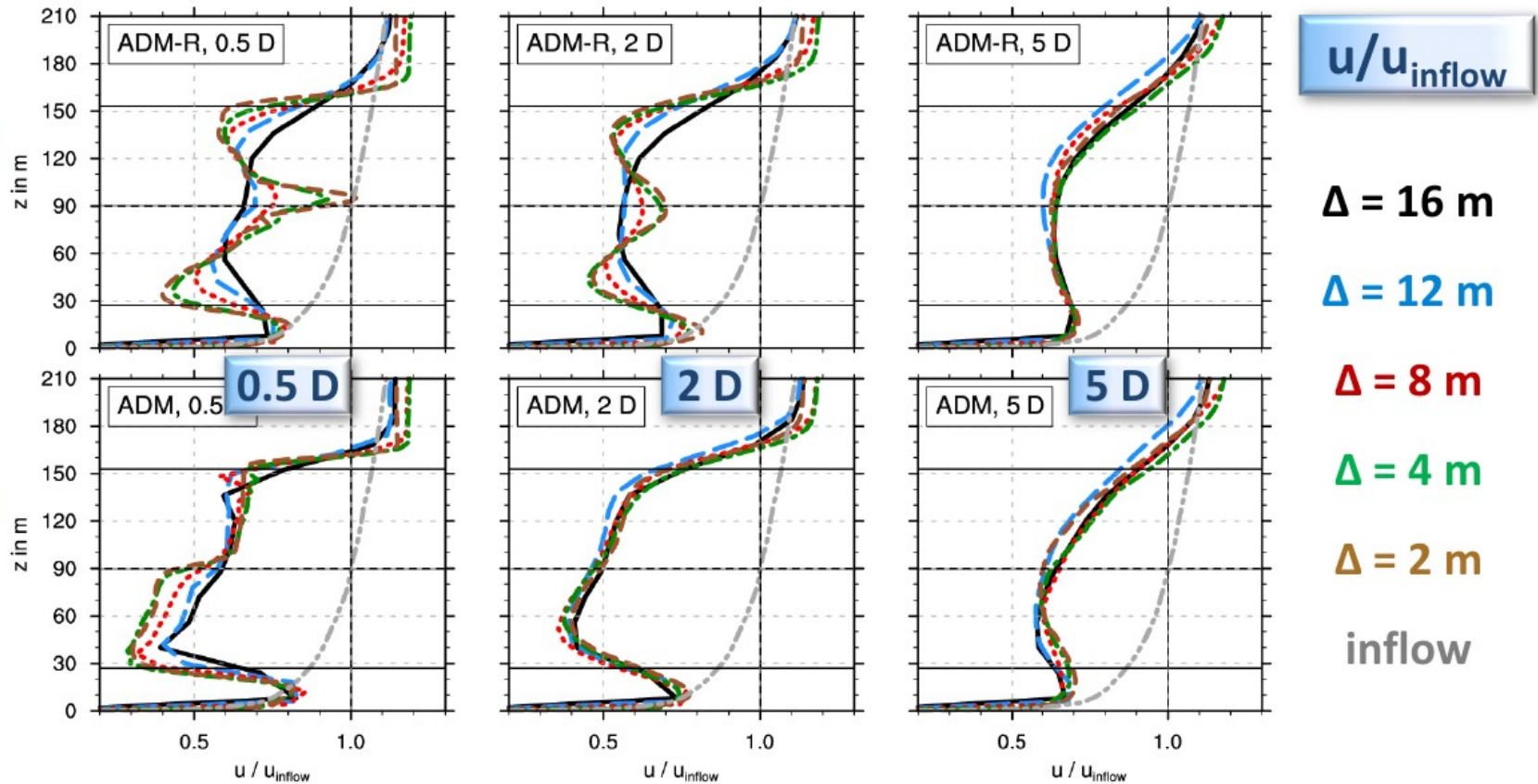
- u -deficit, maximum behind 2nd turbine
- Recovery area due to increased turbulence

Validation: grid sensitivity (ADM-R, T9)



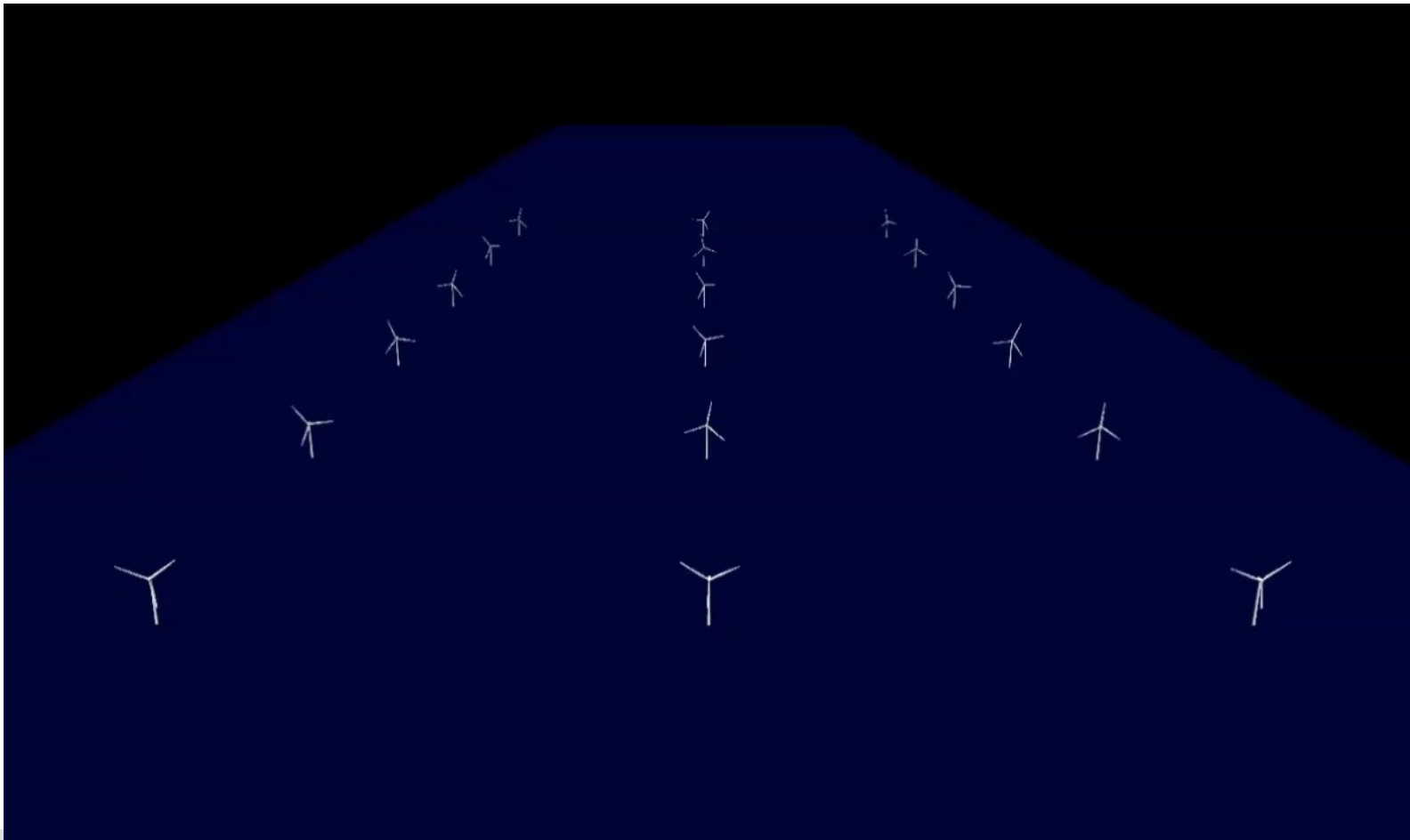
- Large-scale wake structure is well-reproduced at coarse grid
- Finer structures at finer grid spacings

Validation: grid sensitivity (T9)



- Near wake: ADM-R: 30 grid points per rotor required
 } ADM: no sensitivity

Example Application



Useful URLs

- technical documentation:

<https://palm.muk.uni-hannover.de/trac/wiki/doc/tec/wtm>

- description of namelist parameters:

https://docs.palm-model.org/23.04/Reference/LES_Model/Namelist/#wind-turbine-parameters

- example test case:

`palm_model_system/packages/palm/model/tests/cases/wind_turbine_model/INPUT/`