PALM Code Structure & Features

Institute of Meteorology and Climatology, Leibniz Universität Hannover

General remarks

- This lecture gives a brief overview about the code structure of PALM.
- Please note:
  There is ongoing work on further modularization of the PALM code, which will affect parts of the program structure that is presented in this lecture.

Overview

- PALM is written in FORTRAN2008.
- With some very minor exceptions, the code is using the FORTRAN standard, so it should compile without error on any FORTRAN 2003/2008 compiler (90/95 may give problems).
- Machine dependent code segments, e.g. calls of routines from external libraries (e.g. NetCDF or FFTW), which may not be available on some machines, are activated using preprocessor directives.
- The serial and parallel (MPI) PALM version is also activated by preprocessor directives.
- The automatic installer automatically sets the approriate preprocessor directives. For manual settings of directives see https://palm.muk.uni-hannover.de/trac/wiki/doc/app/cpp_options.

Overview

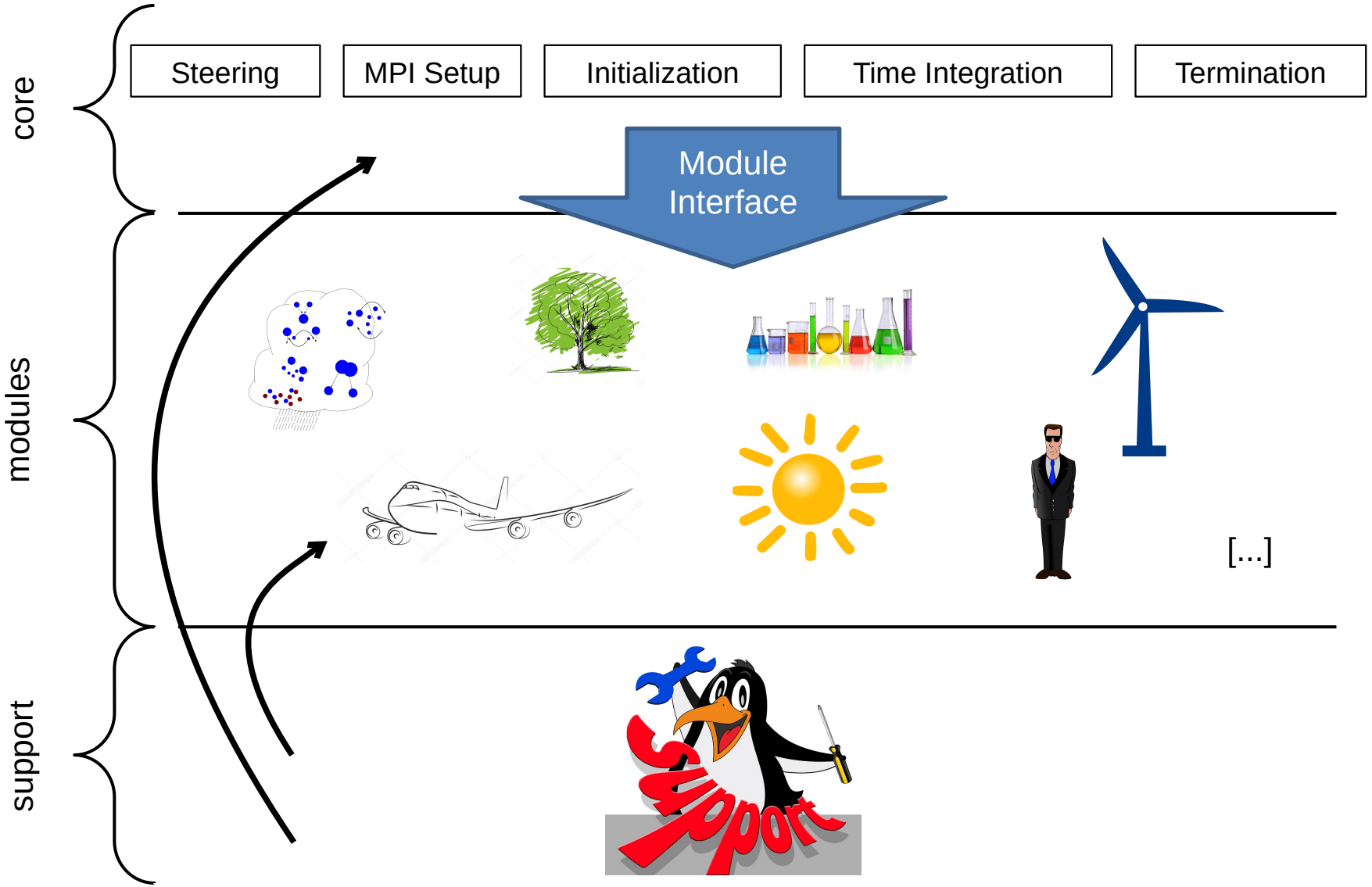
- The code is divided into several files, each file containing:
  - a single MODULE (ending with _mod.f90), including several associated SUBROUTINEs, or
  - a single SUBROUTINE, e.g. file parin.f90 contains SUBROUTINE parin.
- PALM includes a special user module (user_module.f90) designed to add additional code written by the user.

Why should you use the user module instead of directly modiying the source code?

- The user module very rarely changes in future PALM releases and can be easily re-used by newer versions of PALM without requiring extensive changes.

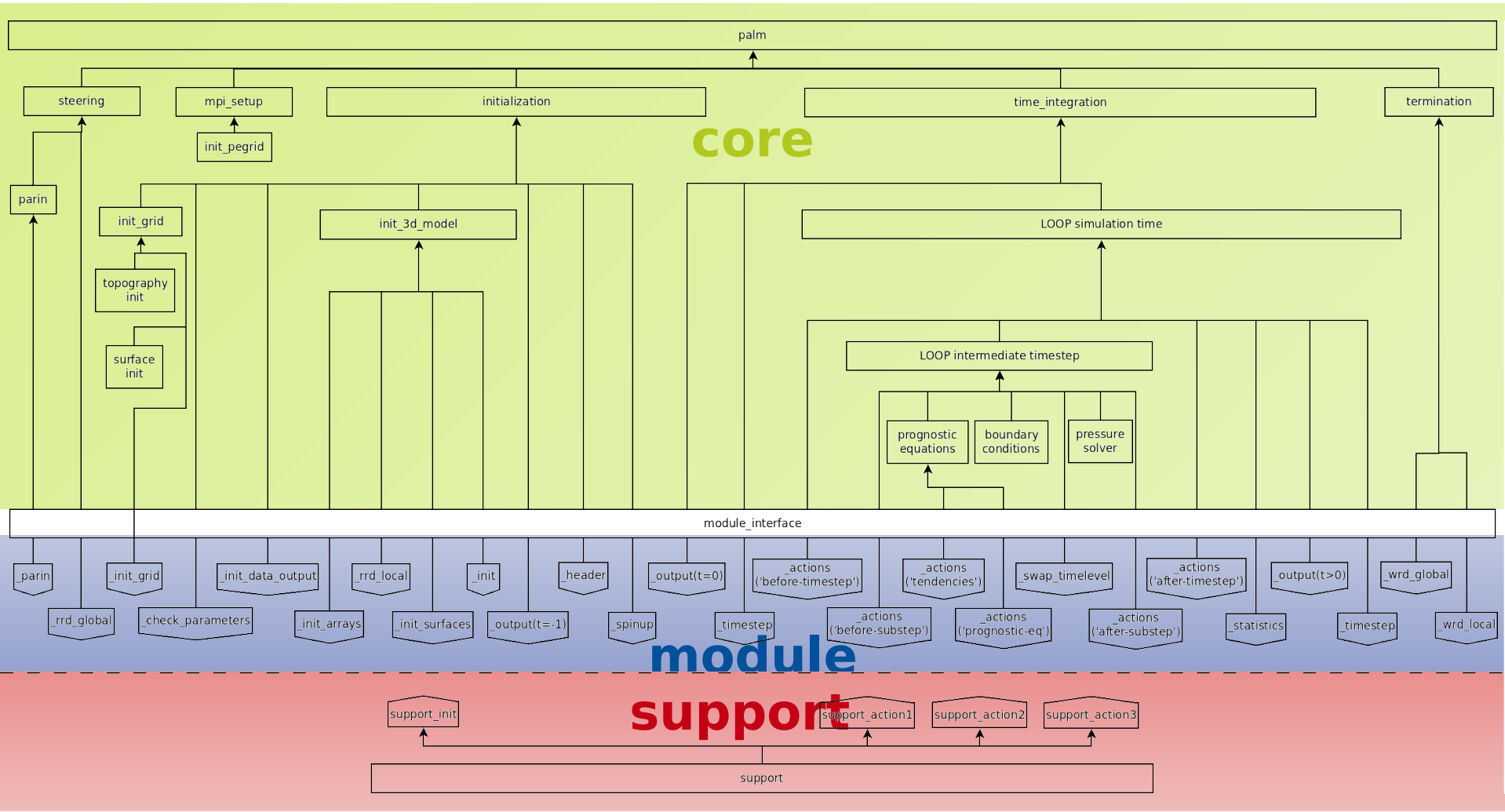
PALM Code Structure & Features

General structure



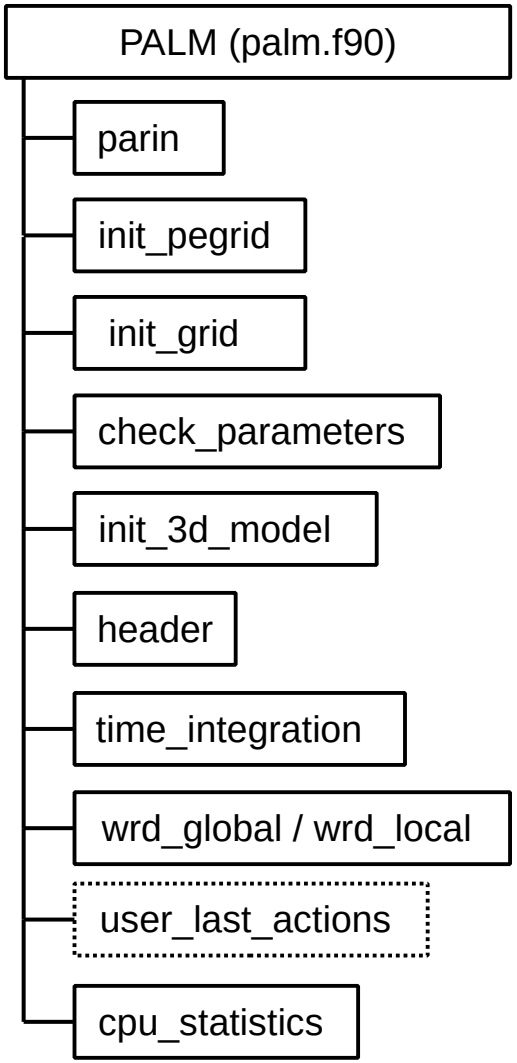
PALM Code Structure & Features

Code structure



PALM Code Structure & Features

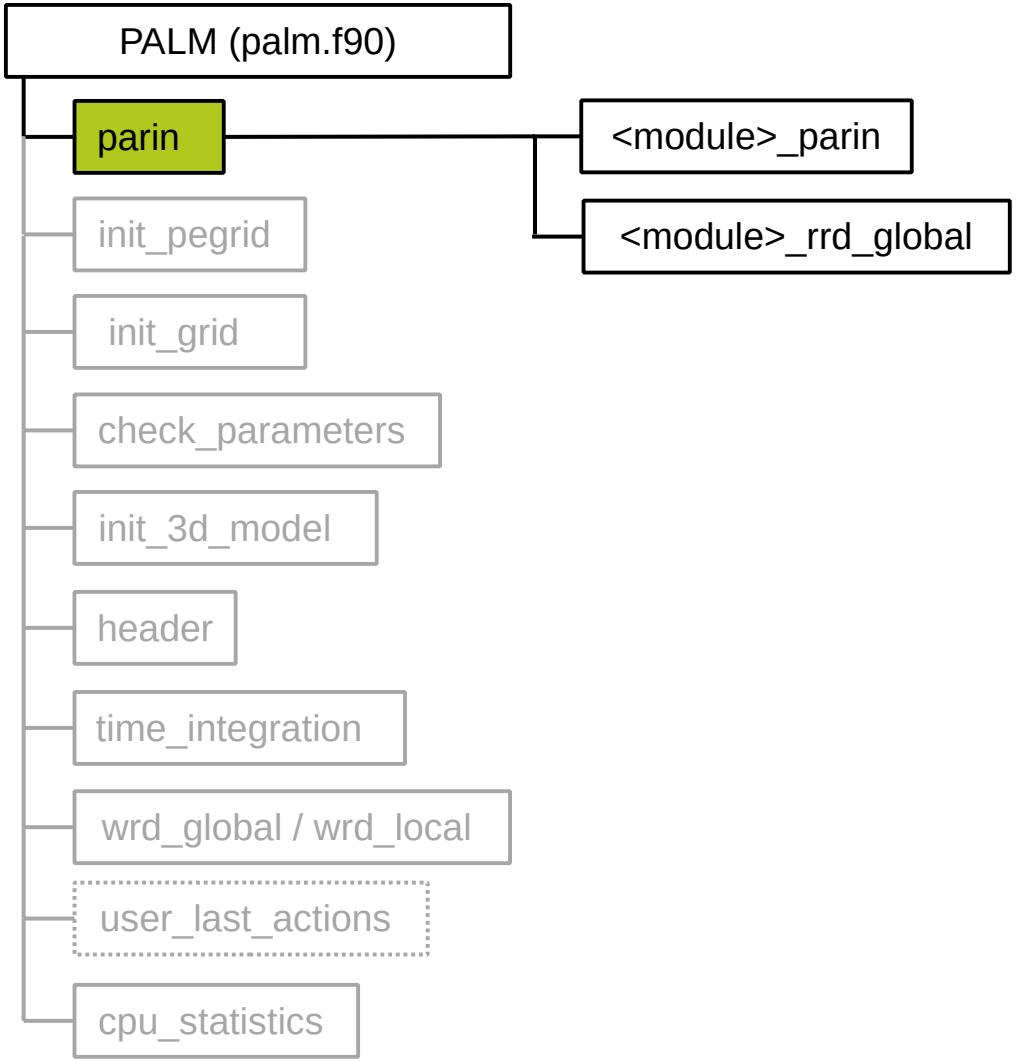
Detailed structure



- Read steering parameters
- Create processor topology (for parallel PALM mode)
- Create grid-depending constants
- Check setting & dependencies of steering parameters
- Allocate arrays and initialize 3D model
- Output important information about current run
- Integrate model equations (statistical analysis, data output)
- Binary output for restarts
- Execute user-defined last actions (if user module is used)
- Output of measured cpu times

PALM Code Structure & Features

Detailed structure

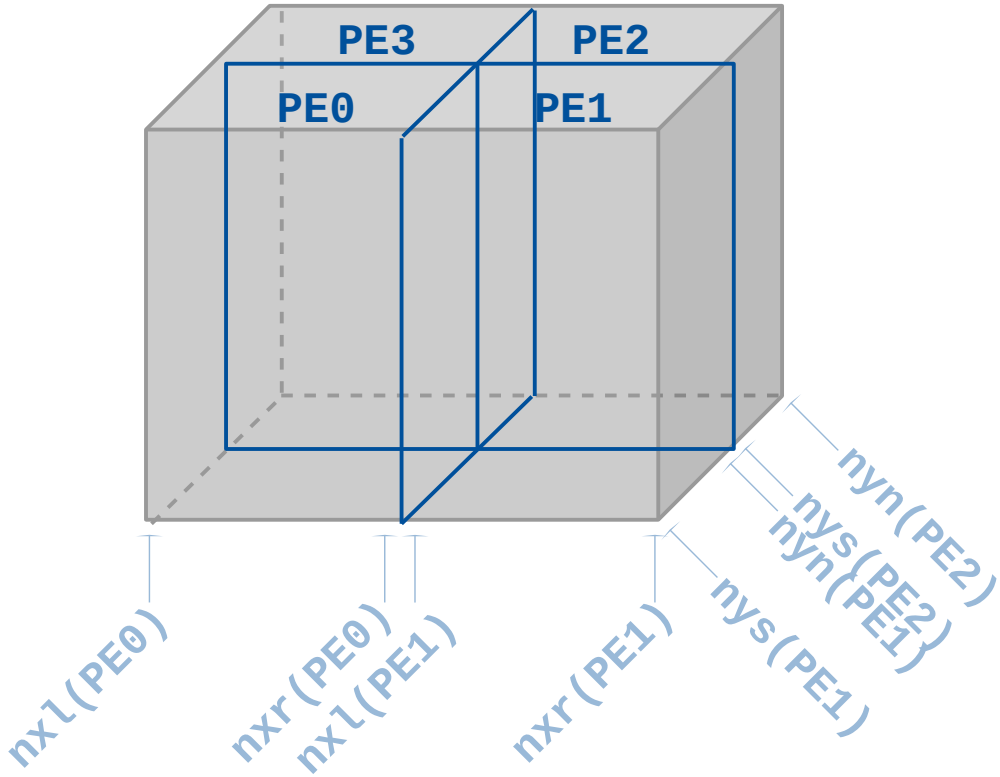


- Read input parameters from namelist file
- Read control parameters from restart file in case of restart run

Detailed structure

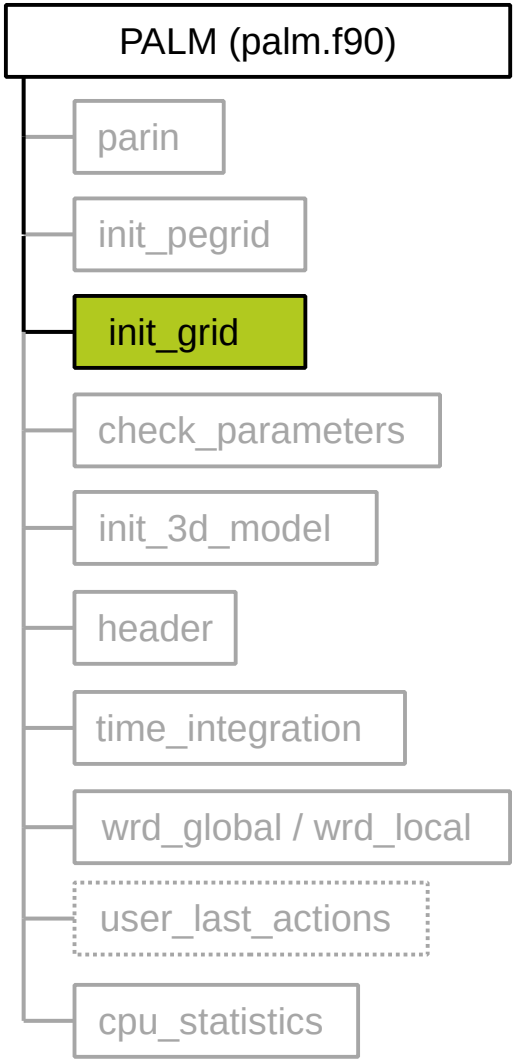
- PALM (palm.f90)
  - parin
  - init_pegrid
  - init_grid
  - check_parameters
  - init_3d_model
  - header
  - time_integration
  - wrd_global / wrd_local
  - user_last_actions
  - cpu_statistics

- Determination of virtual processor topology (if not prescribed by user) & computation of grid point number and array bounds of local subdomains

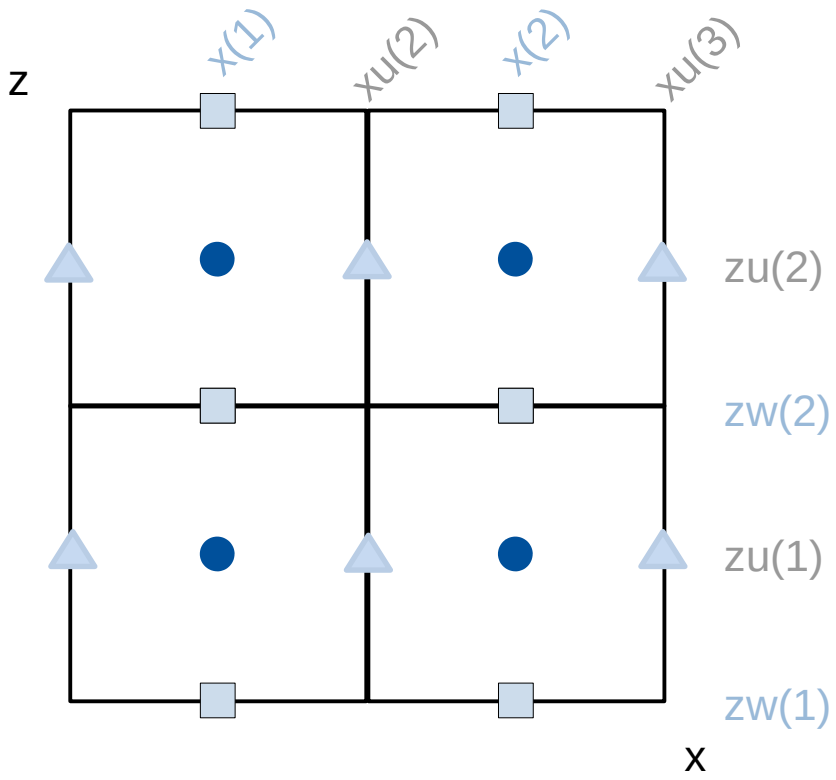


PALM Code Structure & Features

Detailed structure

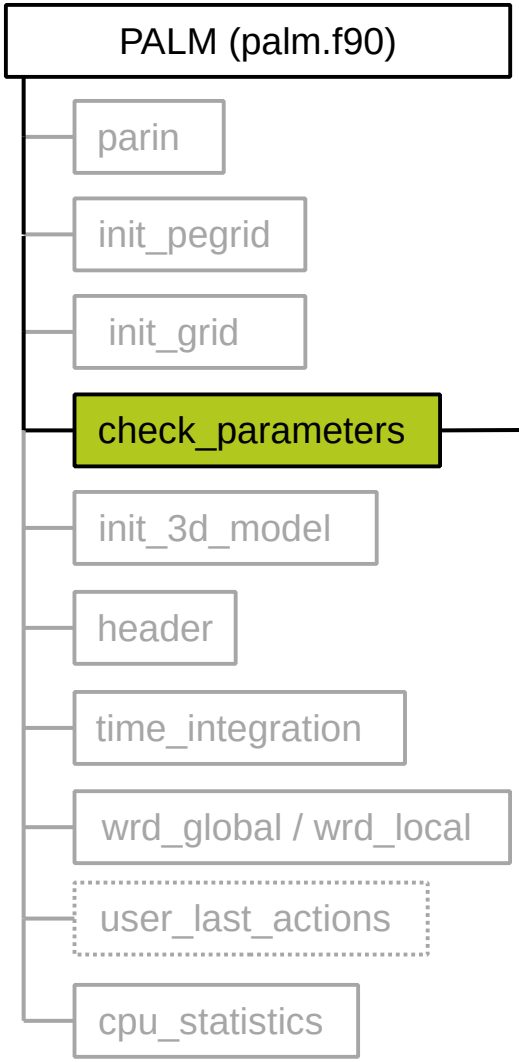


- Pre-calculation of metric grid coordinates on staggered PALM grid, e.g.:



PALM Code Structure & Features

Detailed structure



- Check simulation setup for any inconsistencies
- Check output setup

<module>_check_parameters

<module>_check_data_output_ts

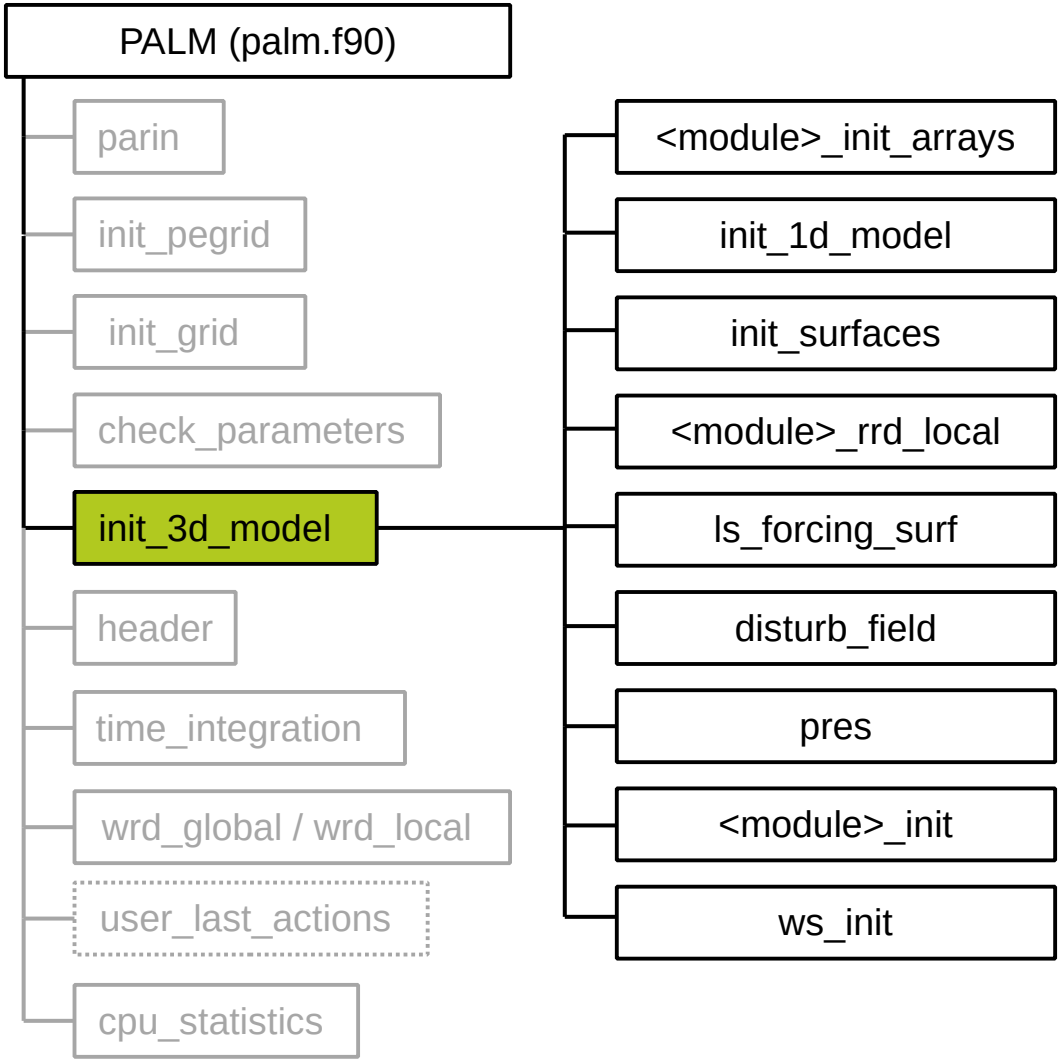
<module>_check_data_output_pr

<module>_check_data_output

In case of any problems, error messages appear in the job protocol, labeled with a specific PALM error code number „PA....“.
Details about error messages can be found at:
https://palm-model.org/trac/wiki/doc/app/errmsg

PALM Code Structure & Features

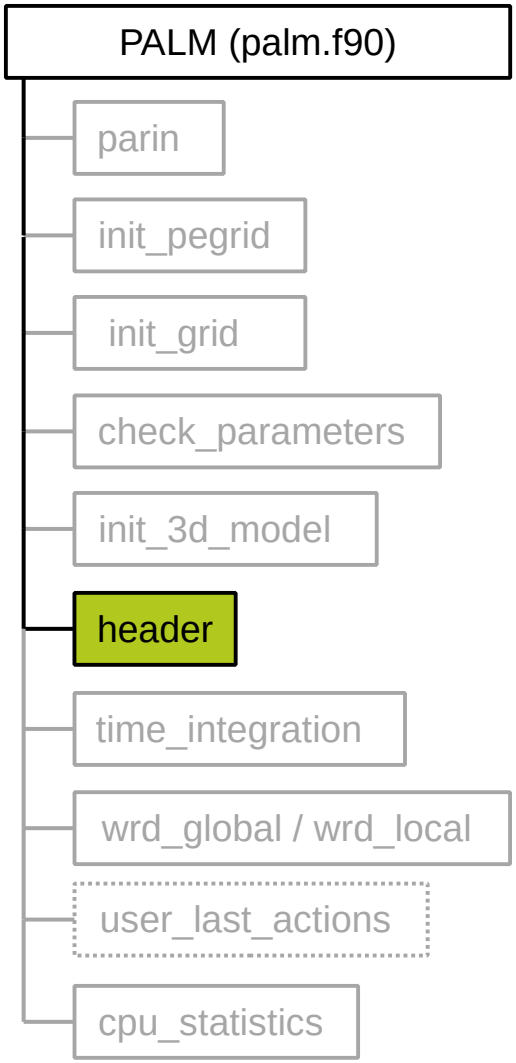
Detailed structure



- Initialize module-specific arrays
- Pre-calculate profiles via 1D model
- Initialize surfaces
- Read arrays from restart data files
- Load large-scale forcing
- Impose random perturbations
- Call pressure solver
- Initialization actions of the modules
- Initialize Wicker-Skamarock scheme

PALM Code Structure & Features

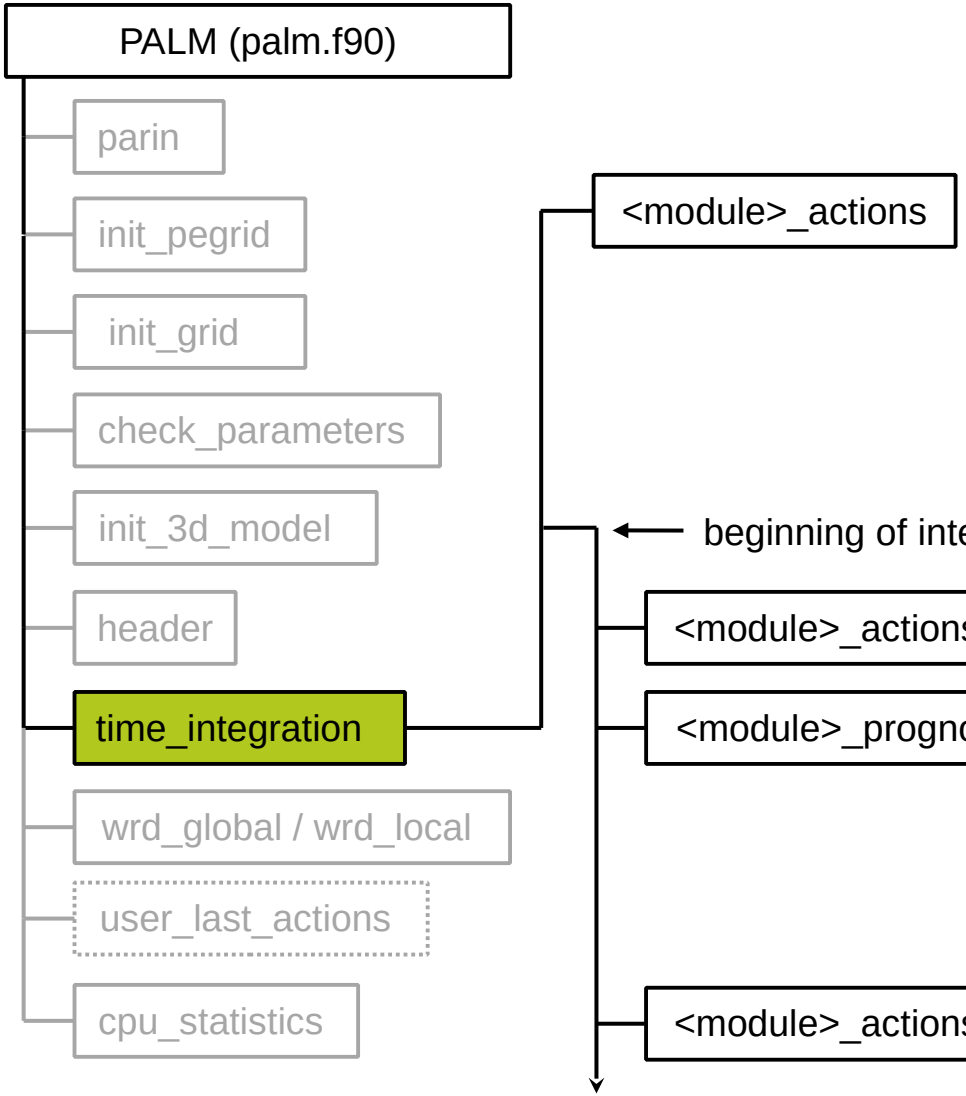
Detailed structure



- Write information about steering parameters to file, useful for job monitoring (see lecture “PALM steering”)

PALM Code Structure & Features

Detailed structure

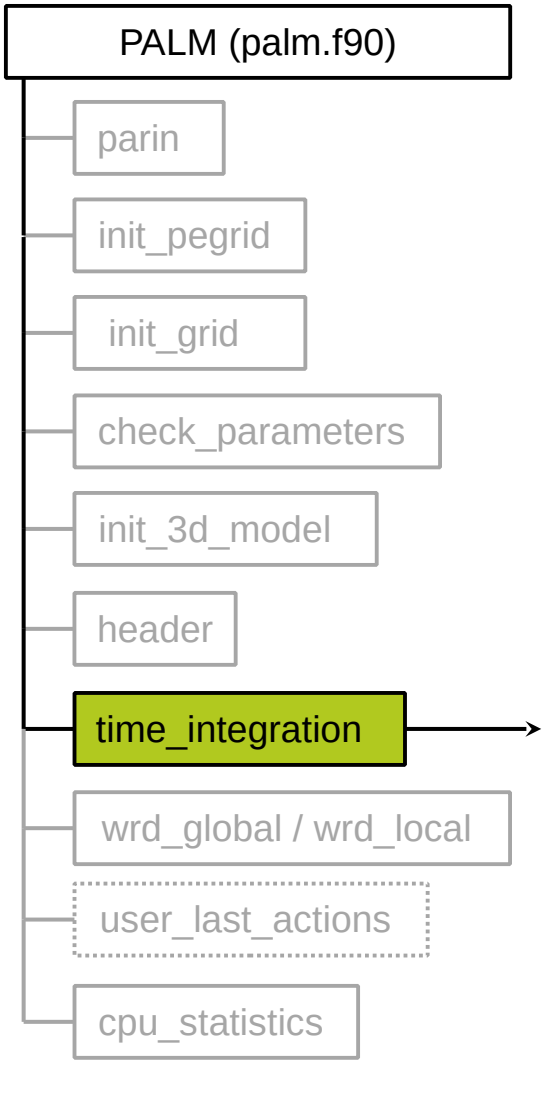


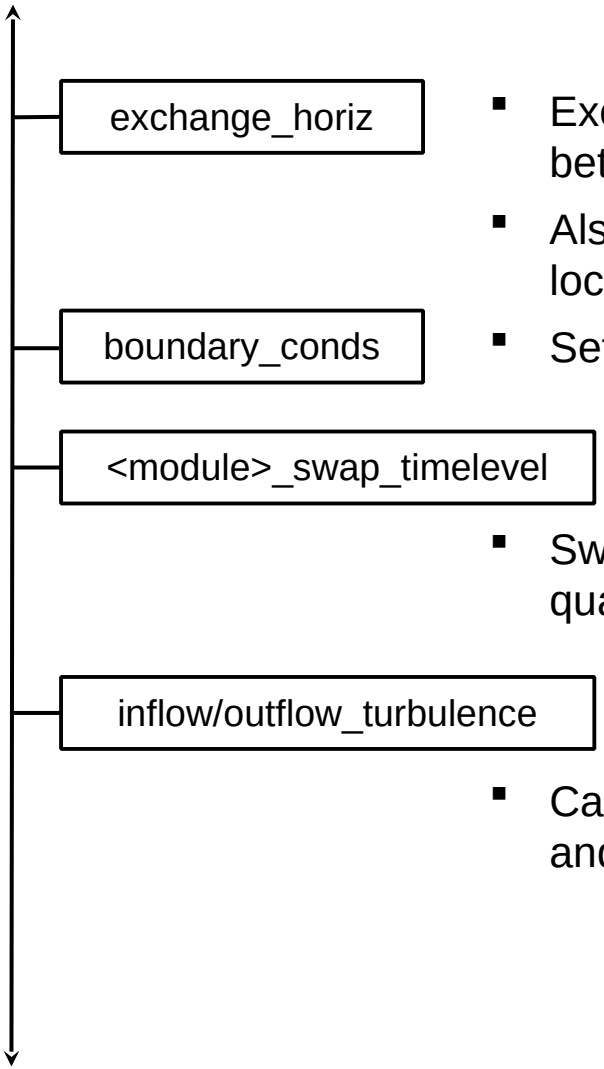
- This is called at several positions throughout `time_integration`
- `<module>_action` has several hooks for different positions inside the time loop
- hooks are addressed via strings, e.g. '`before_timestep`'

- Optimized for different computer architectures
  - cache-based machines
  - vector-based machines

PALM Code Structure & Features

Detailed structure

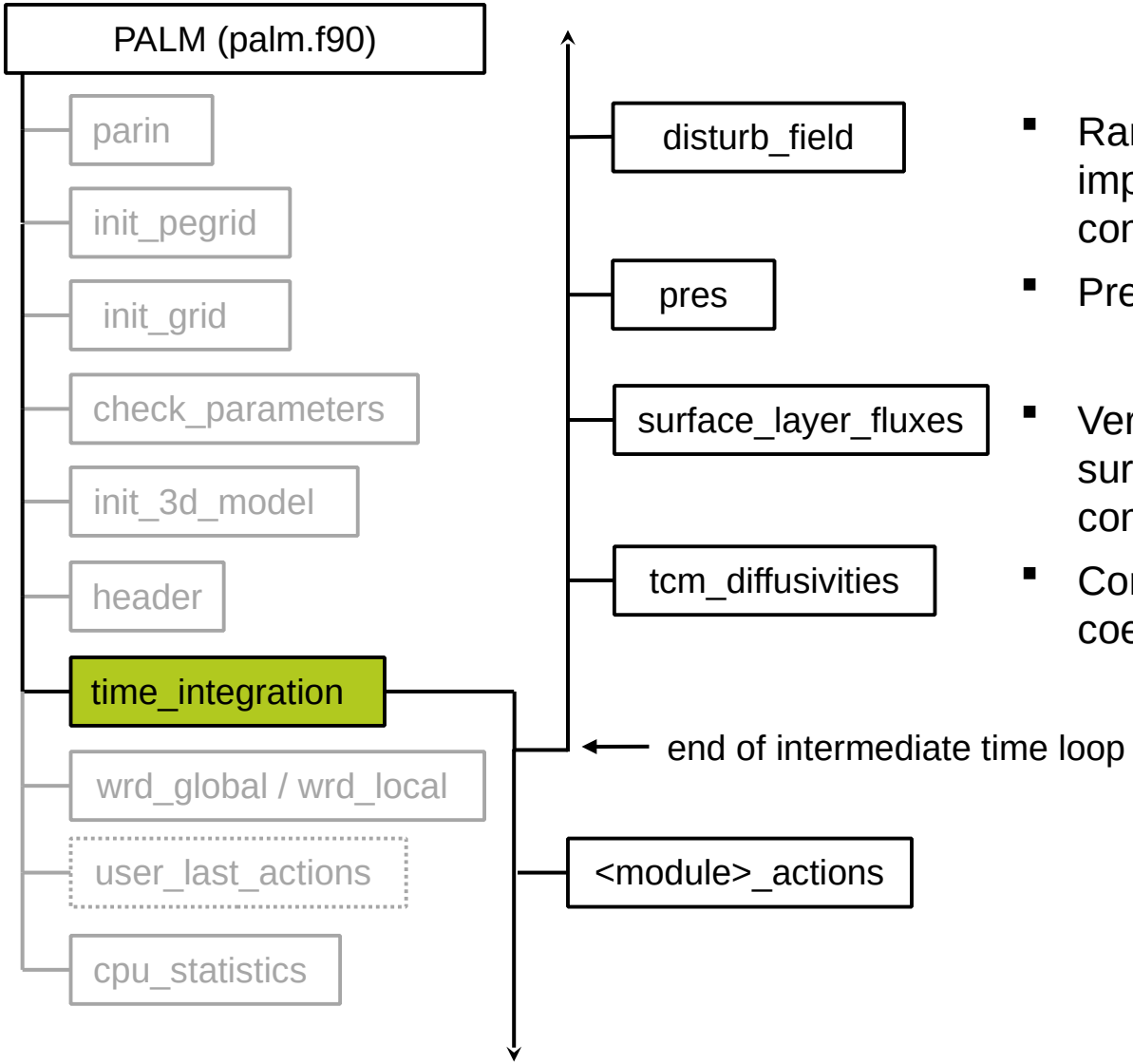




- Exchange of ghost-point data between neighbouring PEs
- Also called at some other locations
- Setting of boundary conditions
- Swapping of prognostic quantities data
- Calculating turbulent inflow and/or outflow conditions

PALM Code Structure & Features

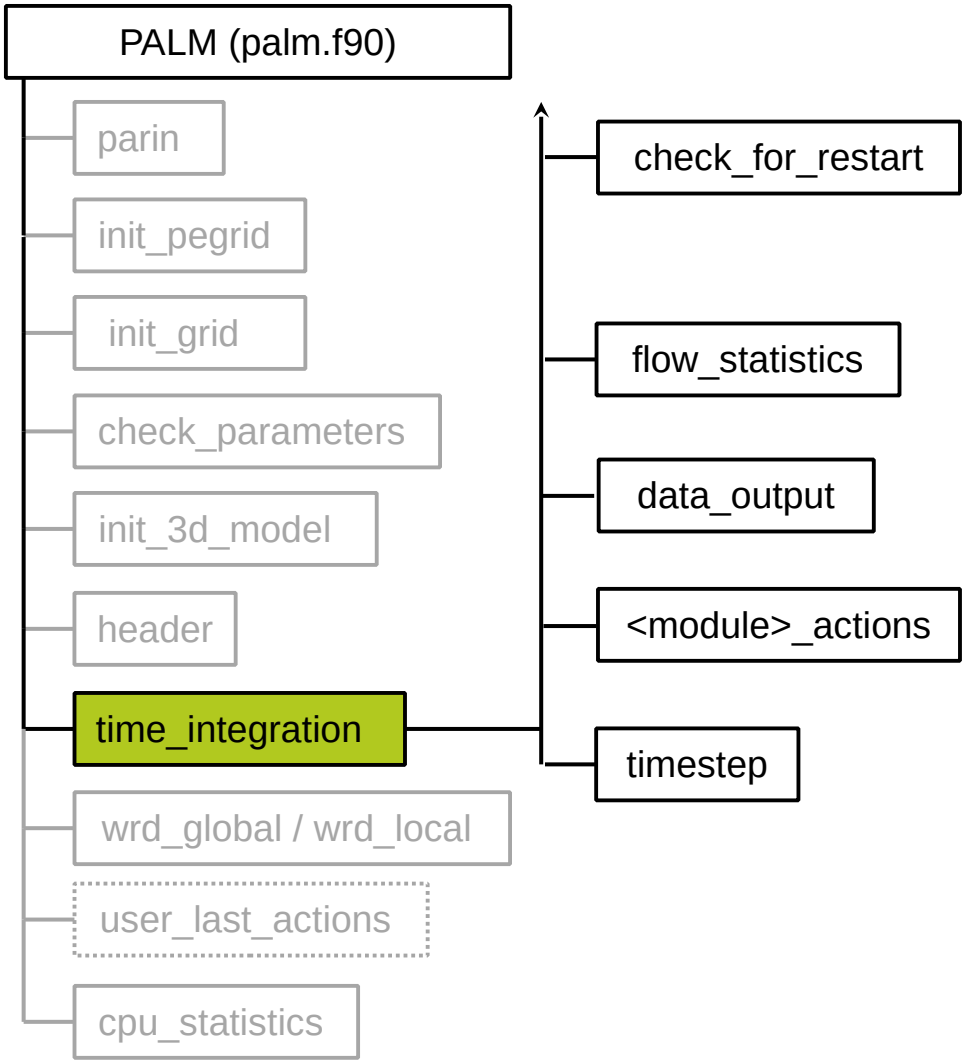
Detailed structure



- Random perturbations are imposed to horizontal velocity components
- Pressure solver
- Vertical turbulent fluxes in the surface (constant-flux) layer are computed
- Computing of diffusion coefficients

PALM Code Structure & Features

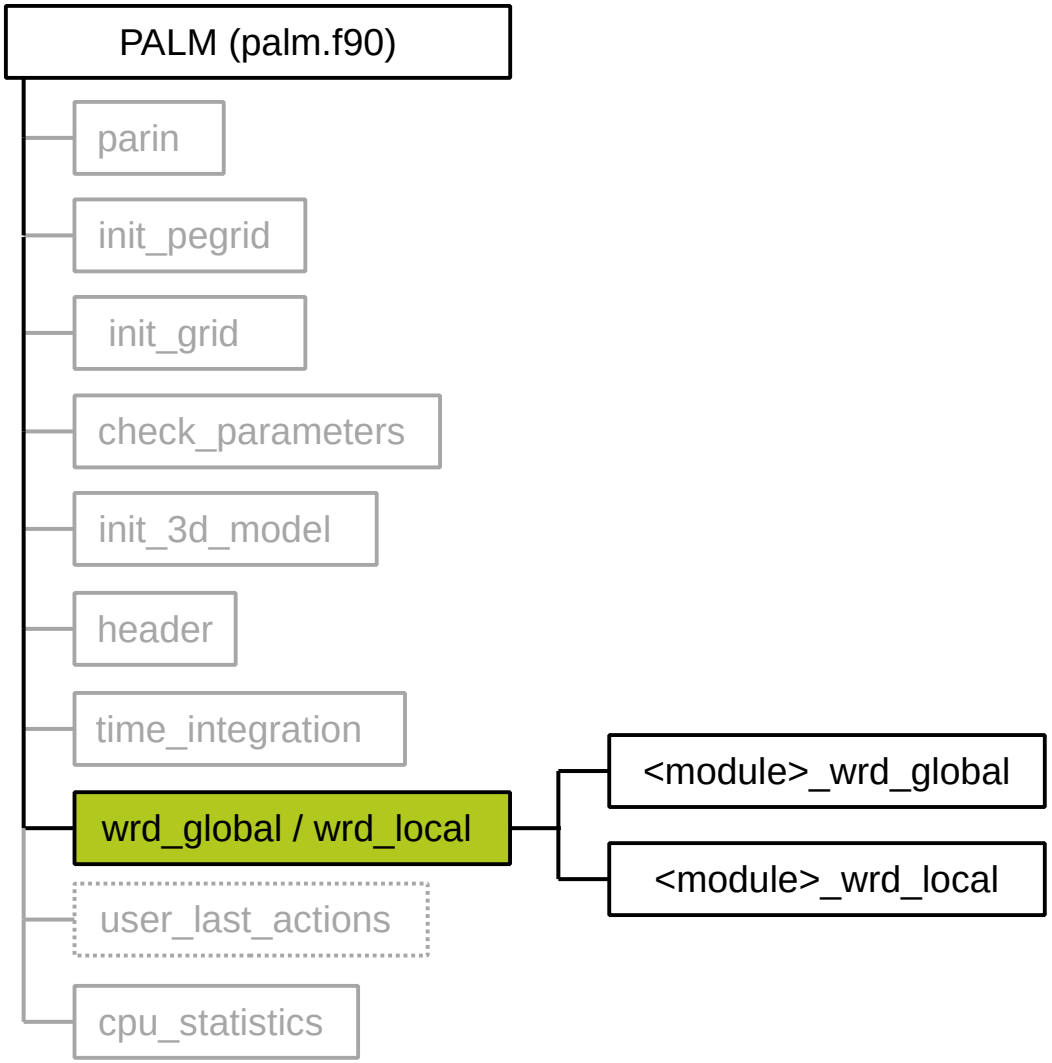
Detailed structure



- Checking if run needs to be terminated (due to insufficient remaining CPU time) and prepare for restart
- Flow statistics are calculated
- Output of requested variables
- Calculating next timestep width

PALM Code Structure & Features

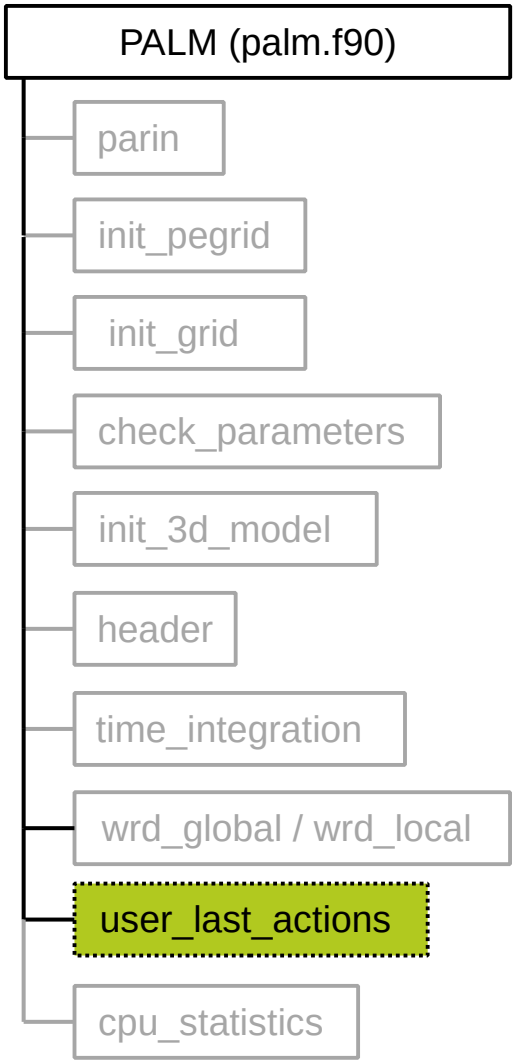
Detailed structure



- Write data required for restarts
  - Steering parameters
  - 3d arrays of prognostic variables

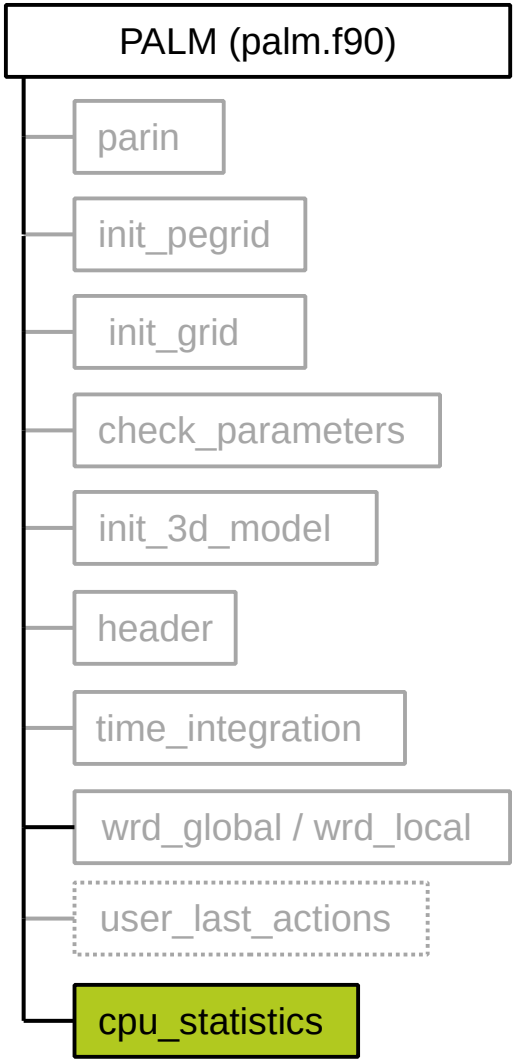
PALM Code Structure & Features

Detailed structure



- Any other last actions before end of simulation

Detailed structure



- Calculate and output information about required CPU time, in total and for certain parts of PALM, e.g. “all progn. equations” or “pres” (see lecture “PALM steering”)

Content – Part 2

- Global variables
- Preprocessor directives
- Automatic documentation using Doxygen
- Important variables and their declaration

Global variables

- Global variables and parameters are defined in **`modules.f90`**
- Only variables that are used in multiple parts of PALM
- Defined in different **`MODULE`**s, e.g., **`pt`** is defined in **`arrays_3d`**:

```
MODULE arrays_3d
[...]
    REAL(wp), DIMENSION(:,:,:), ALLOCATABLE, TARGET :: pt
[...]
END MODULE
```

Global variables

- **USE** statement to load variables in other routines:

```
SUBROUTINE buoyancy( var, wind_component )

    USE arrays_3d,                                 &
        ONLY:  pt, pt_slope_ref, ref_state, tend

    USE control_parameters,                        &
        ONLY:  atmos_ocean_sign, cos_alpha_surface
[...]

END SUBROUTINE buoyancy
```

Preprocessor directives

- Preprocessor directives are special lines in the code which allow to compile alternative parts of the code depending on so-called “**define string** switches“
- Code example:

```
#if defined ( __parallel )
    CALL MPI_ALLREDUCE( a, b, nzt-nzb, MPI_REAL, MPI_SUM,
                        comm2d, ierr )
#else
    b = a
#endif
```

- If the compiler is called as
  `ifort -fpp -D__parallel ...`
  then the **#if** branch is compiled
- If the compiler is called **without** option `-D__parallel`
  the **#else** branch is compiled

Preprocessor directives

- The preprocessor directives require to activate their processing with a specific compiler option, which is e.g. **`-cpp`** for the Intel compiler.
- Preprocessor directives and options have to be given in the **`%cpp_options`** line of the palmrun configuration file **`(.palm.config.<ci>`**, see lecture “PALM steering“)
- Preprocessor options may differ for different compilers
- Define-string switches can be combined using logical AND (**`&&`**) / OR (**`||`**) operators:

```
#if defined( __abc && __def )
#if defined( __abc || __def )
```

- Logical NOT operator:

```
#if ! defined( __abc )
```

Additional use of preprocessor directives

- Replacing strings in the code, e.g.,

```
%cpp_options -cpp -DMPI_REAL=MPI_DOUBLE_PRECISION
```

  replaces **MPI_REAL** with **MPI_DOUBLE_PRECISION** **before** compiling

- Planned use: switch ON/OFF entire modules, e.g. Lagrangian particle model
  - Unnecessary code is not compiled
  - Less compiling time
  - Less memory consumption

List of define-string switches used in PALM

PALM mode	**__parallel**	Parallel PALM version
	__single_precision	Use 32-bit arithmetic (still in test phase)
System specific	**__ibm**	IBM Regatta systems
	__nec	NEC-SX systems
Software specific	**__intel_compiler**	Compilers
	__mpifh	Old MPI libraries
	__netcdf, __netcdf4, __netcdf4_parallel	NetCDF I/O with different NetCDF versions
	__fftw	Fast FFT
	__rrtmg	Radiative transfer model
	__rrtmg	External radiation model library (see lecture)

- Switches set under **%cpp_options** in **.palm.config.<ci>** file are automatically used by **palmbuild** for compiling.

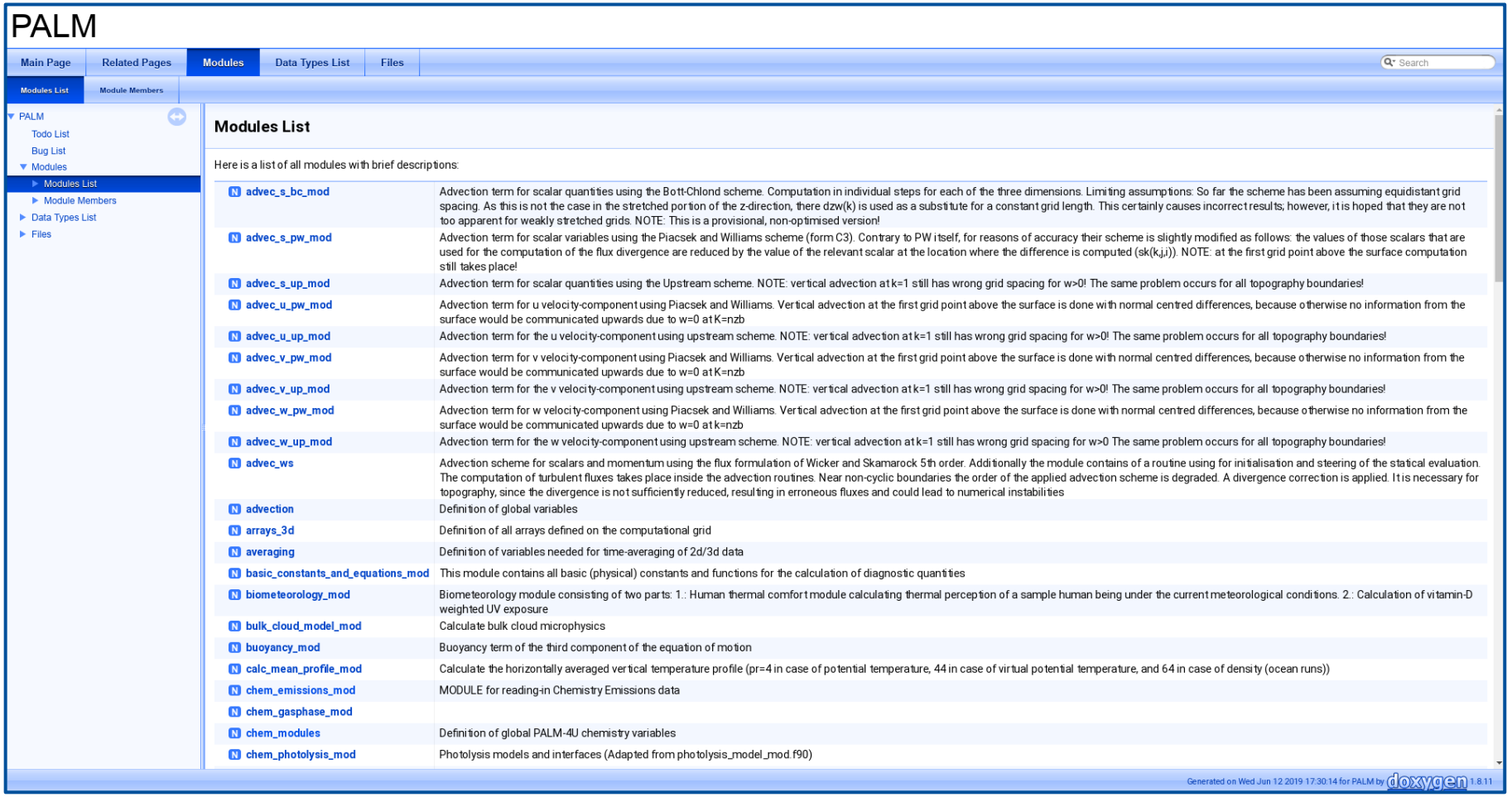
Automatic documentation using Doxygen

- Doxygen:
  "Doxygen is the de facto standard tool for generating documentation from annotated C++ sources, but it also supports other popular programming languages such as [...] ***Fortran*** *[...]."*
- Automatic documentation from the source code via tags.
- **Tags** currently used in PALM:

Description of variables	`REAL :: ol !< Obukhov length`
File/Routine description	`!> This Routine does things`
To do lists	`!> @todo Missing implementation of...`
Bugs	`!> @bug 1D model crashes when...`
Important notes	`!> @note Soil layer must not be` `!>  too thin`

PALM Code Structure & Features

Doxygen demonstration



How to use Doxygen

- Install **Doxygen** and **dot** on your system.
- Run script: **`palmdocs`**
- At the end of the output, **`palmdocs`** will tell you, where to find the newly generated HTML Documentation. To view the docs, open the file **`PALM_doc.html`** in your browser.

Important variables and their declaration

- 3D-arrays of prognostic variables are named Ψ, and Ψ_p for time level t, and $t + \Delta t$, respectively, with $\Psi = u, v, w, pt, q, s, e, sa, ...$

- They are by default declared as $\Psi(z,y,x)$ or $\Psi(k,j,i)$, e.g.

```
u(nzb:nzt+1,nysg:nyng,nxlg:nxrg)
```

with

```
nysg = nys – nbgp,   nyng = nyn + nbgp
nxlg = nxl – nbgp,   nxrg = nxr + nbgp
nzb, nzt   (bottom/top grid index)
nys, nyn   (south/north grid index)
nxl, nxr   (left/right grid index)
```

as the index limits of the (sub-)domain.

- **nbgp** is the number of ghost points which depends on the advection scheme (**nbgp** = 3 for the default Wicker-Skamarock scheme).

Important variables and their declaration

- If only a single process/core is used, then

```
nxl = 0;   nxr = nx
nys = 0;   nyn = ny
```

- For performance optimization, most of the 3D-variables are declared as pointers, e.g.

```
REAL(wp), DIMENSION(:,:,:), POINTER ::  u, u_p
```

- This does not affect the usage of these variables in the code in (almost) any way.

Important variables and their declaration

variable	index bounds	meaning	comment
`zu`	`nzb:nzt+1`	heights of the scalar (u,v) grid levels	`zu(1) = 0.5*dz(1)` `zu(0) = -zu(1)`
`zw`	`nzb:nzt+1`	heights of the w grid levels	`zw(0) = 0`
`dz`	`1:10`	vertical grid spacings	to be set in `&initialization-parameters`
`dzu`	`1:nzt+1`	vertical grid spacings between scalar grid levels	`dzu(k) = zu(k)-zu(k-1)`
`ddzu`	`1:nzt+1`	inverse of grid spacings	`ddzu(k) = 1.0/dzu(k)`
`dx`		grid spacing along x	to be set in `&initialization-parameters`
`ddx`		inverse of `dx`	`ddx(k) = 1.0/dx`
`current_timestep_number`		timestep counter	
`time_since_reference_point`		simulated time in seconds	