

Numerics and Boundary Conditions (used in PALM)

PALM group

Institute of Meteorology and Climatology, Leibniz Universität Hannover

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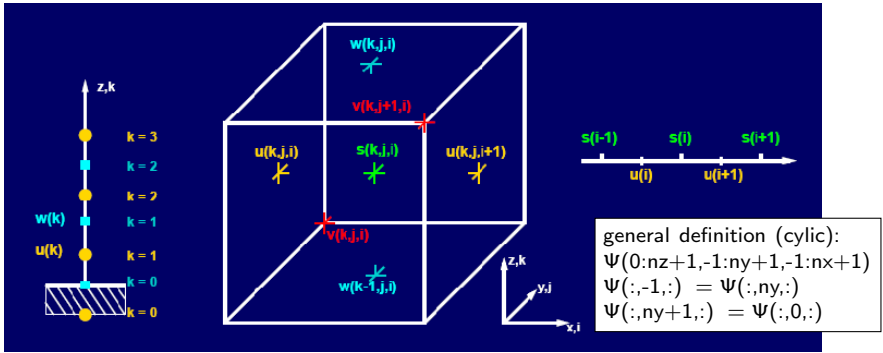
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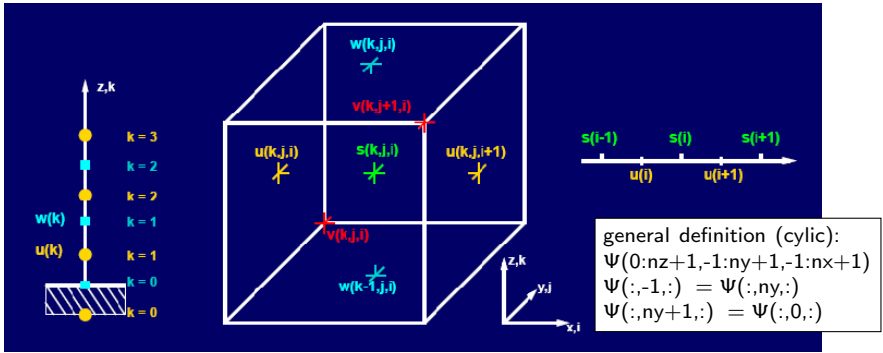
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- ▶ **Boundary conditions:**
 - Cyclic and non-cyclic horizontal boundary conditions
 - Surface layer with Monin-Obukhov similarity
 - Topography
 - Turbulent inflow (for non-cyclic horizontal boundary conditions)

Numerical Grid



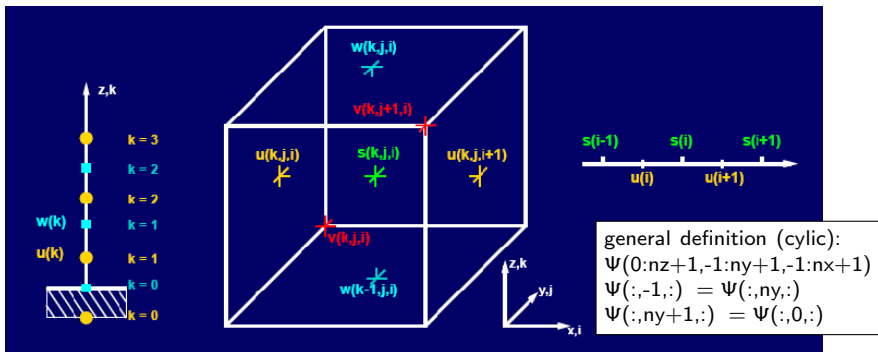
► Equations are spatially discretized on an Arakawa-C grid.

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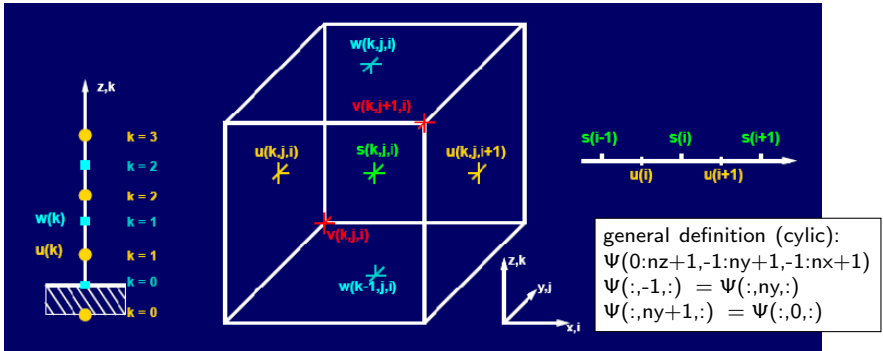
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- ▶ Spacings are equidistant, stretching along z is possible.

Timestep Methods (I)

► **Euler**

$$\frac{\partial\psi(t)}{\partial t} = F(\psi(t)) \rightarrow \frac{\psi(t + \Delta t) - \psi(t)}{\Delta t} \approx F(\psi(t))$$

$$\psi(t + \Delta t) = \psi(t) + \Delta t \cdot F(\psi(t)) \quad \mathcal{O}(\Delta t)$$

(used for SGS-TKE in special cases)

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► Runge-Kutta, third-order

$$k_1 = F(\psi(t))$$

$$k_2 = F\left(\psi(t) + \frac{1}{3} \Delta t \cdot k_1\right)$$

$$k_3 = F\left(\psi(t) - \frac{3}{16} \Delta t \cdot k_1 + \frac{15}{16} \Delta t \cdot k_2\right)$$

$$\psi(t + \Delta t) = \psi(t) + \frac{1}{30} \Delta t (5k_1 + 9k_2 + 16k_3) \quad \mathcal{O}(\Delta t^2) \quad C \leq 0.9$$

Timestep Methods (II)

In the PALM code, the different timestep schemes are treated by one equation using switches:

$$\psi(t+\Delta t) = (1-c_1) \cdot \psi(t-\Delta t) + c_1 \cdot \psi(t) + \Delta t \cdot [c_2 \cdot F(\psi(t)) + c_3 \cdot F(\psi(t-\Delta t))]$$

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Scheme	c_1	c_2	c_3
Euler	1	1	0
RK (1st step)	1	1/3	0
RK (2nd step)	1	15/16	-25/48
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$$\psi(t-\Delta t) = \psi(t)$$

after each RK substep

$$\psi(t) = \psi(t+\Delta t)$$

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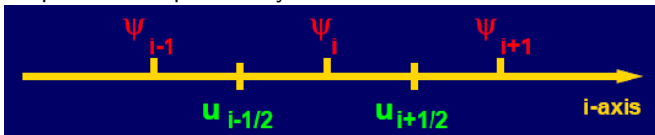
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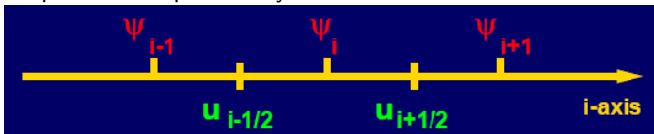
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$$\left. \frac{\partial(u\psi)}{\partial x} \right|_i = \frac{1}{2\Delta x} \left(u_{i+\frac{1}{2}}\psi_{i+1} - u_{i-\frac{1}{2}}\psi_{i-1} \right)$$

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- ▶ In case of momentum advection (e.g. $\psi = u$), u_{i-1} and u_{i+1} have to be obtained by linear interpolation.
- ▶ May cause $2\Delta x$ wiggles in case of sharp gradients.

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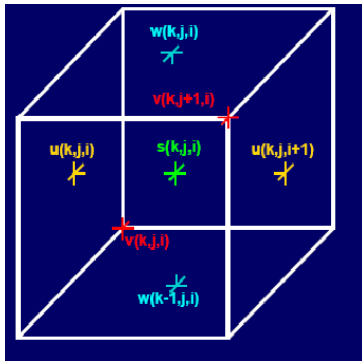
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 - Adds additional numerical dissipation

Advection Methods – Wicker/Skamarock (I)

- ▶ Wicker and Skamarock (2002, Mon. Wea. Rev. 130, 2088 – 2097).
- ▶ Based on flux form of advection term
- ▶ Difference of fluxes at the edge of the grid cell is used to discretise advection term



$$\frac{\partial \psi}{\partial t} = -\nabla(u_i \psi) \approx -\frac{F_{i+\frac{1}{2}} - F_{i-\frac{1}{2}}}{\Delta x}$$

Advection Methods – Wicker/Skamarock (II)

Finite difference approximation of 6th order

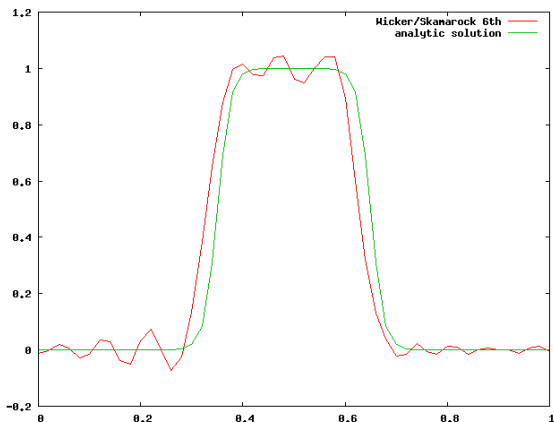
$$F_{i-\frac{1}{2}}^{6\text{th}} = \frac{1}{60} u_{i-\frac{1}{2}} (37(\Psi_i + \Psi_{i-1}) - 8(\Psi_{i+1} + \Psi_{i-2}) + (\Psi_{i+2} + \Psi_{i-3}))$$

Artificially added numerical dissipation term

$$-\frac{1}{60} \left| u_{i-\frac{1}{2}} \right| (10(\Psi_i - \Psi_{i-1}) - 5(\Psi_{i+1} - \Psi_{i-2}) + (\Psi_{i+2} - \Psi_{i-3}))$$

Advection Methods – Wicker/Skamarock (III)

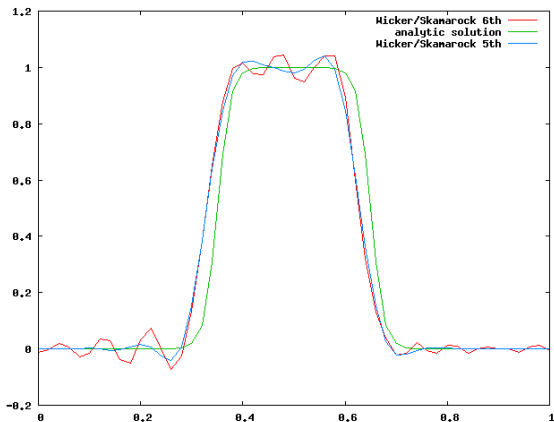
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Centered Finite Differences produces numerical oscillations ("wiggles") near sharp gradients.

Advection Methods – Wicker/Skamarock (IV)

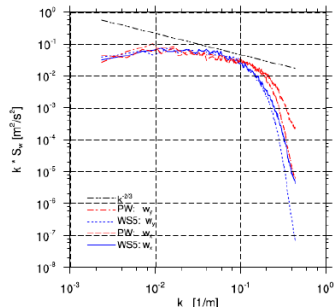
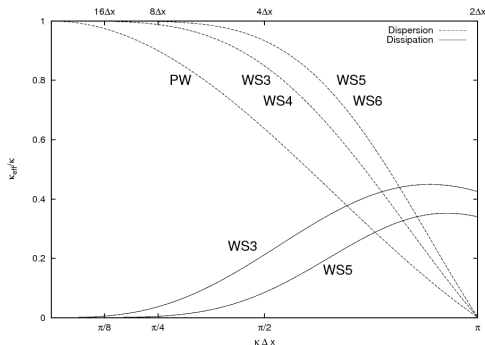
$$F_{i-\frac{1}{2}}^{5th} = F_{i-\frac{1}{2}}^{6th} - \frac{1}{60} |u_{i-\frac{1}{2}}| (10(\Psi_i - \Psi_{i-1}) - 5(\Psi_{i+1} - \Psi_{i-2}) + (\Psi_{i+2} - \Psi_{i-3}))$$



Advantage
 Numerical Dissipation
 damps small scale
 oscillations.

Disadvantage
 In a turbulent flow
 numerical dissipation
 removes energy from
 small scales.

Advection Methods – Wicker/Skamarock (V)



- ▶ Better resolution of larger scales ($> 8 \Delta x$) and hence less numerical energy transfer from larger to smaller scales compared to lower order schemes.
- ▶ Less spectral energy at smaller scales.

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- ▶ Incompressibility is reached by a predictor-corrector method
 1. Momentum equations are solved without the pressure term giving a provisional velocity field which is not free of divergence.

$$\bar{u}_{i_{\text{prov}}}^{t+\Delta t} = \bar{u}_i^t + \Delta t \left(-\frac{\partial}{\partial x_k} \bar{u}_k^t \bar{u}_i^t - (\varepsilon_{ijk} f_j \bar{u}_k^t - \varepsilon_{i3k} f_3 u_{gk}) + \mathbf{g} \frac{\bar{\theta}^{*t}}{\theta_0} \delta_{i3} - \frac{\partial}{\partial x_k} \overline{u'_k u'_i}^t \right)$$

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2. Assign all remaining divergences to the (perturbation) pressure p^* so that the new corrected velocity field is the sum of the provisional, divergent field and the perturbation pressure term.

$$\overline{u}_i^{t+\Delta t} = \overline{u}_{i_{\text{prov}}}^{t+\Delta t} + \Delta t \left(-\frac{1}{\rho_0} \frac{\partial \overline{p}^{*t}}{\partial x_i} \right)$$

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4. After solving the Poisson equation, the final velocity field is calculated as given in step 2.

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 - ▶ Requires periodic boundary conditions and uniform grids along x and y

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- ▶ Iterative solver

basic idea: Poisson equation is transformed to a fixed point problem:

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Depending on the structure of the matrix T and vector c different iterative solvers can be defined, e.g.: Jacobi-scheme (here on 2D-uniform grid):

$$p_{i,j}^{k+1} = \frac{1}{4} \cdot \left(p_{i-1,j}^k + p_{i+1,j}^k + p_{i,j-1}^k + p_{i,j+1}^k - \Delta x^2 f(i,j,k) \right)$$

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- ▶ Iterative schemes are 'local schemes' → information is needed only from neighboring grid-points.
- ▶ Very low convergence: $\mathcal{O}(n^2)$.

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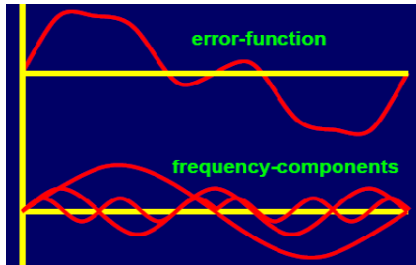
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- ▶ The main idea of the multigrid method is to reduce errors of different frequencies on grids with different grid spacing:
 - ▶ errors of high frequency are reduced on fine grids
 - ▶ errors of low frequency are reduced on coarse grids.

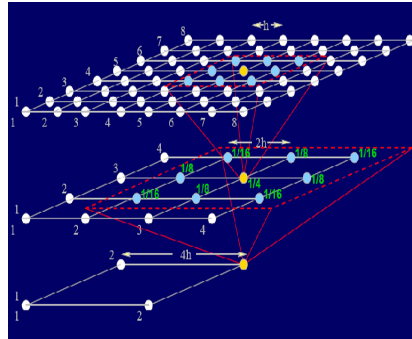


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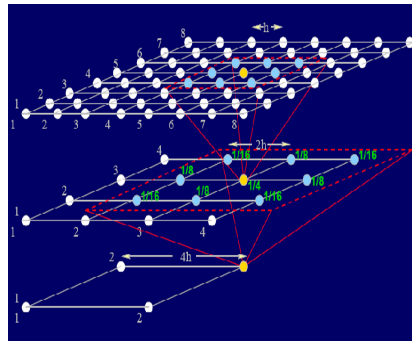
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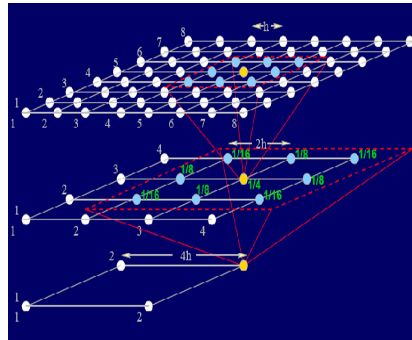
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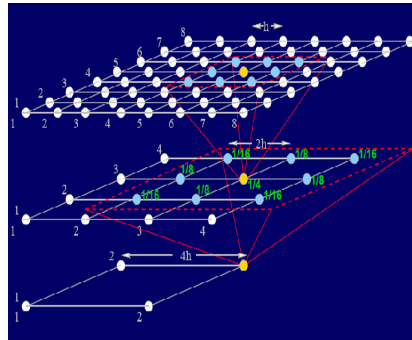
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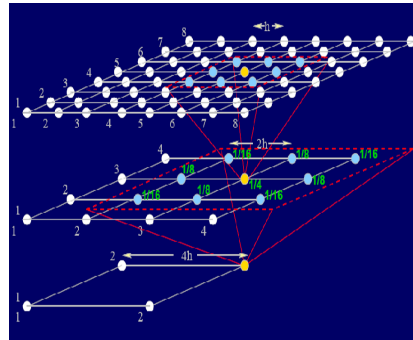
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- V- and W-cycles are implemented.



Boundary Conditions (I)

- ▶ Lateral (xy) boundary conditions:
 - ▶ Cyclic by default, allowing undisturbed evolution / advection of turbulence.



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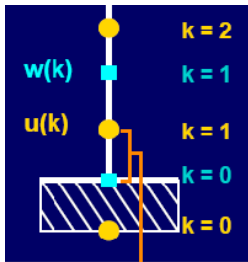
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- ▶ Surface boundary condition:
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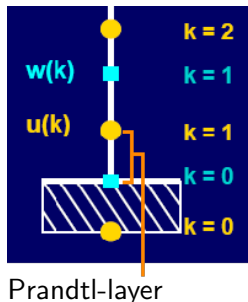
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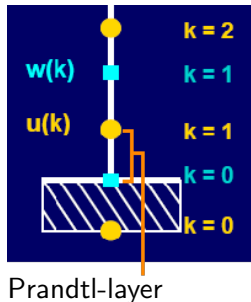
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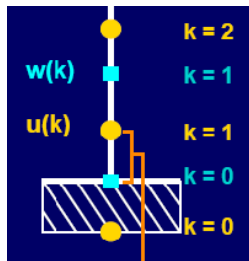
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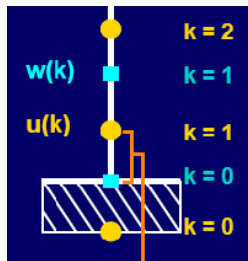
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Under horizontally homogeneous initial conditions, random fluctuations have to be added in order to generate turbulence!